



ABS M5 Kit

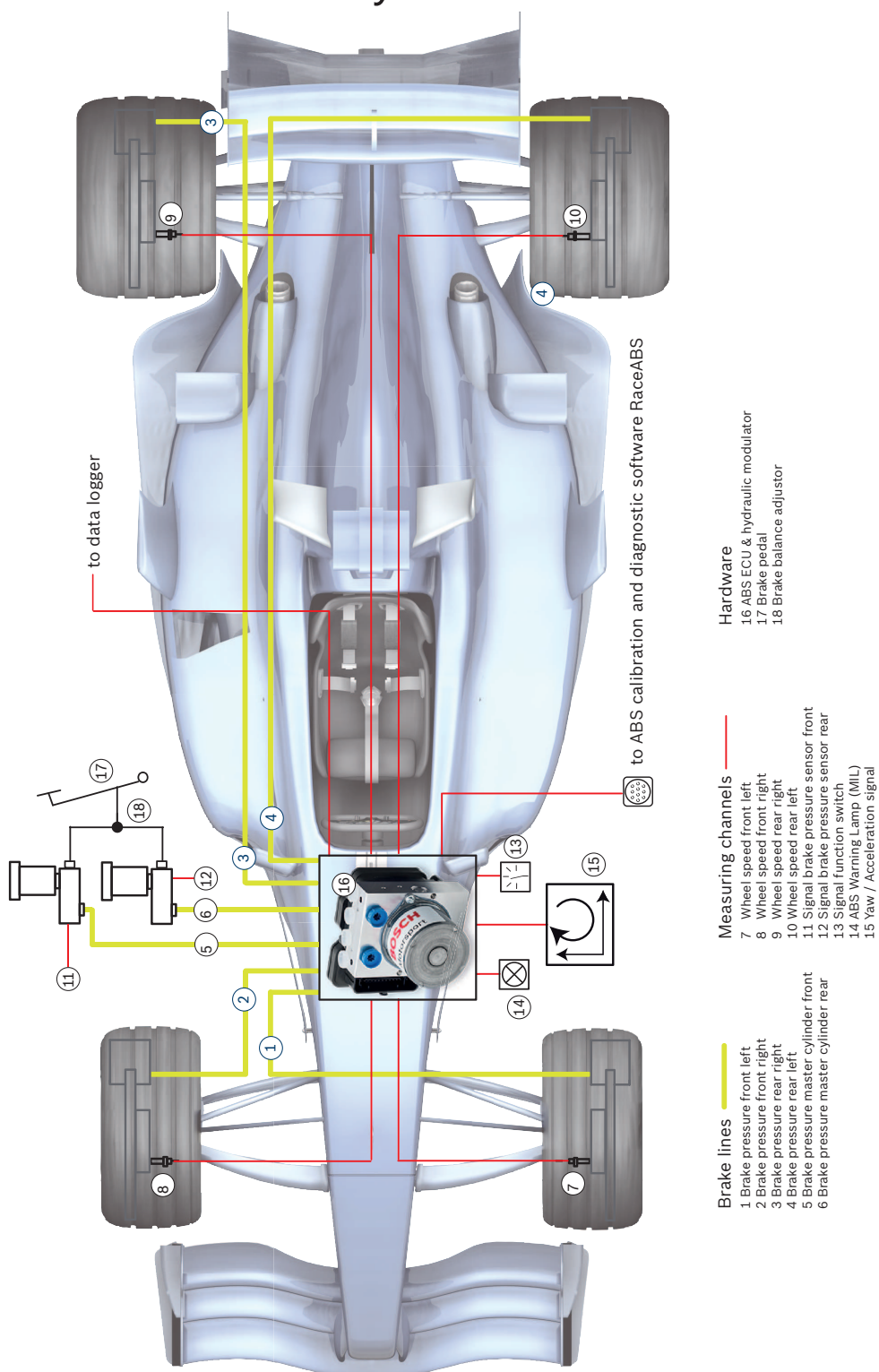
Manual

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1 System Overview



2 Before Use

Read these instructions carefully and follow the recommendations for use step by step. We are happy to give you additional notes and explanations. Our contact information is on the back cover of this manual.

2.1 Safety Information



DANGER

For use by professionals exclusively.

Using the system does not come without risks.

The ABS M5 Kit was developed for use by professionals and requires in-depth knowledge of automobile technology and experience in motorsport. Using the system does not come without its risks.



WARNING

Use on public roads prohibited.

Bosch shall not be held responsible or liable for damages caused from use on public roads.

It is the duty of the customer to use the system for motor racing purposes only and not on public roads. We accept no responsibility for the reliability of the system on public roads. If the system is used on public roads, we shall not be held responsible or liable for damages.

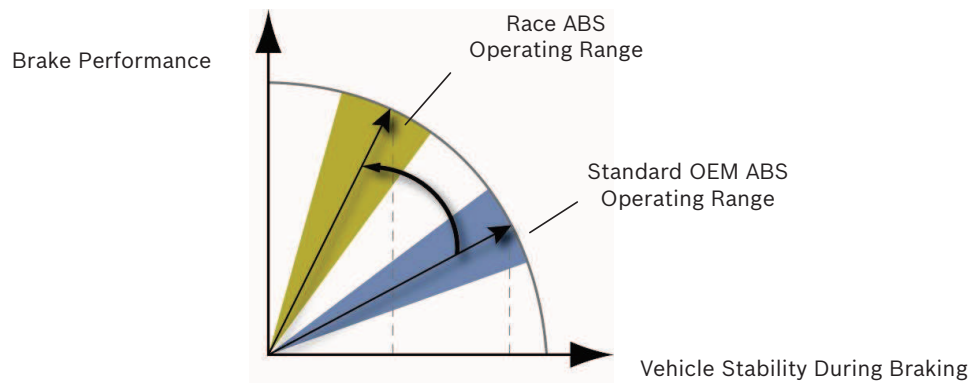
Any maintenance or repair must be performed by authorized and qualified personnel approved by Bosch Motorsport.

All system parts are designed to work together and may not be replaced with similar parts without our expressed permission (this includes the wiring harness). For first time purchases, each team or owner must purchase a complete kit, which includes a wiring harness. Spare parts may be purchased after a complete kit has been purchased. The use of unauthorized parts or wiring harnesses will not be supported by Bosch Motorsport; additionally the system cannot be guaranteed to work properly and/or without limitations.

It is essential that the predefined Bosch Motorsport assembly guidelines are complied with the system to run properly, see section Assembling the Parts ► 18]. This applies above all for installing the MIL (malfunction indication lamp) within the driver's range of visibility.

2.2 ABS in Motorsport

The ABS function is a compromise between drivability and braking performance. Drivability is the primary focus for passenger based vehicles. The ABS is designed to keep the passenger vehicle maneuverable and stable under any circumstances and under any conceivable driving conditions.



In a motorsport context, this compromise shifts towards braking performance, as experienced drivers can still control a slightly unstable vehicle. Together with different tire structures and higher braking potential, a racecar is capable of greatly increased deceleration rates. To consider different chassis tuning and tires, ABS M5 has eleven control settings plus an OFF-position. With this, the driver can choose the best setting for his vehicle. For calibration drives, the ABS function can be deactivated separately, whereby all ABS sensor signals are transmitted and processed furthermore (OFF-position of the ABS switch).

2.3 Principle of Operation

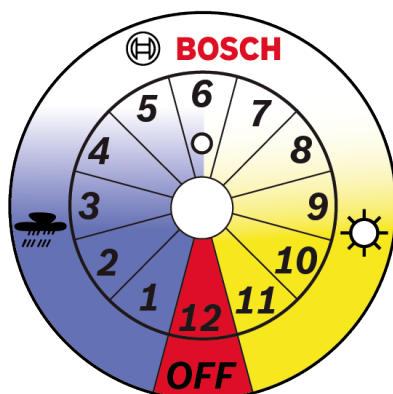
ABS M5 is suitable for **front-wheel, rear-wheel and four-wheel drive vehicles**. It is based on a series production ABS M5 and adapted in years of development work to meet motorsport requirements, e.g. FIA requirements for using only eight active valves.

The ABS M5 prevents the wheels from locking during braking. It does this by constantly measuring the individual wheel speeds and comparing them with the vehicle speed predicted by the system. If, during braking, the measured wheel speed deviates from the system's predicted vehicle speed, the ABS M5 controller takes over, correcting the brake force to keep the wheel at the optimum slip level and so achieving the highest possible deceleration rate. This is carried out separately for each wheel.

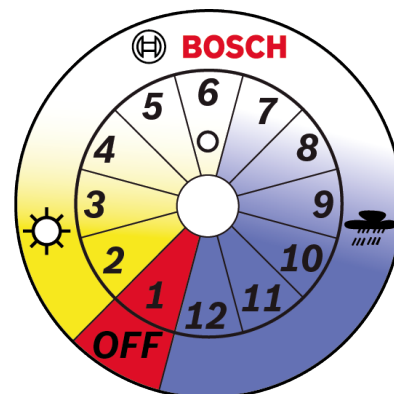
When the brake force is reduced by the ABS M5, brake fluid is released from the brake caliper and fed into the pressure reservoir of the hydraulic power unit of the ABS M5. The hydraulic power unit then feeds the fluid back into the master cylinder via a piston pump driven by an electric motor. The driver can hear this return pumping of the brake fluid and feel the response of the brake pedal.

2.4 Features

Note: In the following, we only refer to the *ABS M5 scale, standard*. You can use the *ABS M5 scale, alternative*, if your ABS M5 is switched off in position 1.



ABS M5 scale, standard



ABS M5 scale, alternative

The ABS M5 has eleven different control settings, selectable via a switch in the cockpit (position 1 to 11 with OFF on position 12 or position 2 to 12 with OFF on position 1). The ABS map switch in the cockpit enables the driver to select various control settings stored in the control device. Using the standard ABS scale, it starts with switch position 1 for the most sensitive controller setting (e.g. heavy rain condition). The configured control settings allow progressively more slip as the position of the dial gets numerically higher. With switch position 11, the most aggressive settings are achieved. Your optimal setting is not necessarily the most aggressive.

- Calibration
In case of need, the calibration of the 11 control maps can be done by Bosch Motorsport ABS engineers.
- Switch off ABS functions for calibration drives
Switching off the ABS functions can be very helpful, e.g. for adjustment of the brake balance bar. OFF-position will be signaled by lit MIL (Malfunction Indication Lamp). All ABS sensor signals will still be communicated. ABS should be turned off in any case where the drive wheels are spinning while the car is stationary, e.g. during warm-up or when on the dynamometer. No error entry will take place.
- Measuring vehicle dynamics
Due to specially-adapted chassis and tires, racing vehicles allow for significantly higher longitudinal and lateral acceleration rates than series production vehicles. Our ABS M5 sensors constantly measure vehicle acceleration and lateral forces as well as the pressure of the front and rear brake circuit.
- Programming and diagnosis software
Each ABS M5 can be configured with specific data related to the vehicle, such as vehicle mass, wheelbase, track width, tire rolling circumference, etc. Should the vehicle data change at any time, you can adapt the system settings by using the RaceABS diagnostic software. You find the software for free download on our website www.bosch-motorsport.com. The new RaceABS diagnostic tool will also work with older ABS M4 systems.
- Performing a system function test
The system function test can diagnose the functional capability without having to move the vehicle.
- Reading data from the error log
Any missing part or incorrectly connected electrical connection of ABS operation-critical components are signaled by a lit MIL. In the error log you can read and analyze what errors have set the MIL and then delete the errors after the issue has been resolved. Noncritical faults are stored without activating the MIL.

- Repair Bleeding Wizzard
Step-by-step instructions will guide you through bleeding the ABS unit, see also Repair Bleeding Wizard [► 32].
- Connectivity for data loggers and displays
You can connect a data logger (e.g. the C 70 from Bosch Motorsport) to the ABS-Wiring-Harness via CAN. The CAN Bus can give you wheel speeds and other readings from the system. All ABS M5 CAN messages can be displayed on any programmable, CAN-compatible display (e.g. the DDU 9 und DDU 10 from Bosch Motorsport), see also chapter “CAN Protocol V19 customer from 0700 onwards [► 41]”.
- Switch the system on and off
Switch the system on or off via switch in the cockpit.
- Reset the system
Reset the system by switching to position OFF and back to ON.

3 Technical Data

Variations

| Option | Kit 1 | Kit 2 | Clubsport |
|--|-------|-------|--|
| F02U.V05.2 | 89-01 | 90-01 | 91-01 92-01 93-01 94-01 95-01 96-01 |
| Customized wiring loom | + | + | - |
| ABS-Off position optional on position 1 | + | + | - |
| Selection of ABS maps via Bosch 12-position switch or via specified CAN signal | + | + | +* |
| Motorsport connectors for wheel speed sensors | - | + | - |
| Flexible CAN terminals | + | + | +** |
| Downforce depending slip regulation | +*** | +*** | - |
| Lateral acceleration slip regulation | + | + | - |
| Corner inside wheel slip reduction regulation | + | + | - |

+*: fixed Kit Content

+**: Adjustable via Coding Plug

+***: Enabled with customer specific calibration

Mechanical Data

| Hydraulic unit | |
|--------------------------------------|---|
| Serial housing, dust- and damp-proof | |
| Vibration damped circuit board | |
| 38 pin connector | |
| 2 hydraulic valves per wheel | |
| 2 brake circuits (front and rear) | |
| 2 hydraulic high pressures pumps | |
| 2 hydraulic accumulators | 3 cm ³ /each |
| Standard fittings | 2 x master cylinders M12 x 1 4 x brake cylinders M10 x 1 |
| Size | 122 x 110 x 122 mm |
| Operating temperature | -30 to 130°C |
| Max. shock | 50 g less than 6 ms |
| Max. working speed | 360 km/h = 100 m/s = 224 mph |

Pressure Medium

| |
|---------------------|
| DOT 4 brake fluid |
| DOT 5.1 brake fluid |

Electrical Data

| | |
|-------------------------------|---------------------------------|
| Supply voltage | 10 to 16 V, max. 24 V for 5 min |
| Max. peak voltage | 35 V for 200 ms |
| Power consumption Pump | 230 W |
| Power consumption Relay | 170 W |
| Power consumption Electronics | 8 W |

Inputs

| |
|---|
| 4 active wheel speed DF11i, DF11S or DF11V |
| Brake pressure (front brake circuit / rear brake circuit) |
| Longitudinal acceleration, lateral acceleration, yaw rate (MM5.10 sensor) |
| 11 adjustment settings (applicable for OEMs) |
| ABS function can be deactivated (Pos. 1 or Pos. 12) |

Outputs

| |
|--|
| ABS warning light (MIL) |
| EBD warning light (MIL) if needed |
| TTL wheel speed signal FL / FR / RL / RR |

Content of Kit and Weights

| | |
|--|--------------------|
| Hydraulic unit | 1,910 g |
| 2 pressure sensors | 40 g/each |
| Yaw/acceleration sensor | 60 g |
| 12 position function switch | 50 g |
| 4 wheel speed sensors DF11 standard | 50 g/each |
| ABS warning light (MIL) | 50 g |
| Vehicle specific wiring harness with motorsport connectors | Depends on version |
| Clubsport wiring harness | 1,540 g |
| Mounting and vibration-damping boards | 80 g |
| Mounting board for hydraulic unit | 212 g |

Optional Accessories

| | |
|---|-----------------|
| Data logger C 70 | F02U.V02.302-02 |
| Display DDU 9 | F02U.V02.300-03 |
| Display DDU 10 | F02U.V02.659-02 |
| Communication interface MSA Box II | F02U.V00.327-03 |
| Wheel speed signal splitter with 1 motorsport connector | F02U.V00.335-03 |

Communication

| | |
|-------------------------|------------|
| ABS and Yaw rate sensor | CAN1 |
| Diagnostics | MSA Box II |

4 Disposal

Hardware, accessories and packaging should be sorted for recycling in an environment-friendly manner.

Do not dispose of this electronic device in your household waste.

5 Adaptations to your Vehicle

Physical vehicle data

For optimum brake performance, each ABS M5 unit has to be customized to suit the vehicle in which it is to be used. To do this, the system can be programmed by the user with certain data, such as the vehicle weight, vehicle dimensions, wheel circumference, and wheel weight. The system then uses this data as basis for calculation. Bosch will also program this data ahead prior to delivery; however, it is very important that you calibrate or verify the data prior to operating the vehicle.

You can find a form to fill in your vehicle data on www.bosch-motorsport.com. This form should be provided to you by your dealer with the order of the kit if the kit shall be programmed by Bosch.

Wiring harness

Each ABS system is delivered with a wiring harness that we have specifically created in accordance with customer requests.

With every Clubsport ABS you receive a standard wiring harness, which is not customized. Please see Wiring Harness ABS M5 Clubsport [► 54].



CAUTION

Use of ABS M4 wiring loom on ABS M5 system will damage the unit.

Though the connectors of both systems are identical, both systems require their own wiring loom.

System environment and related requirements

Is the ABS system being used as a closed stand-alone system? Or is it net-worked with a control unit?

If the system is networked with a standard control unit, we recommend that you use our speed/acceleration sensor with a CAN rate of 500 kBaud to avoid compatibility issues. Check the CAN speed in order to choose the same value for the ABS Kit.

If the system is networked with a motorsport control unit or used as self-sufficient stand-alone-system, we recommend that you use our speed/acceleration sensor with a CAN rate of 1 MBaud. This version features a greater measuring range.

If the system is networked with an ECU MS 6 or MS 7, we recommend that you use our speed/acceleration sensor with a CAN rate of 1 MBaud to avoid compatibility issues.



NOTICE

To avoid message ID conflicts care should be taken when networking with a production CAN bus.

Was or is the vehicle already fitted with an ABS system? Was or is it an old BOSCH ABS system?

ABS M5 requires signals from differential dual Hall sensors such as the Bosch DF11 or similar to function correctly. These sensor types are used in new vehicles for ABS and ESP® systems and can be carried over for the ABS M5. The DF11 sensor element was first deployed by Bosch in 2006. Conventional inductive and Hall sensors found in older series

production ABS units will not function as transmitters for the ABS M5. If your vehicle contains an older ABS system, you have to remove the wheel speed sensors and replace them by the sensors included in the package to be able to use the ABS M5.

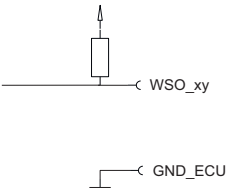
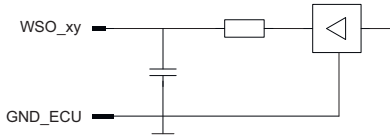
If you are not sure if your sensors are compatible with ABS M5, Bosch Motorsport will gladly check that for you.

If you are fitting your vehicle with an ABS system for the first time, you may need an encoder wheel for each wheel and a sensor mount to record the wheel speeds. Please pay attention to the fitting position of the wheel speed sensors.

Do the wheel speed signals need to be communicated to other control units?

1. Option CAN
2. Option Wheel Speed TTL

ABS M5 delivers wheel speed Hall signals for FL, FR, RL and RR wheels as output. Connector is available on wiring harness under Wheel Speed TTL for FL, FR, RL and RR, see also System Overview [► 4]. The following graphic shows the spec as it is in the ECU. An example of the front left wheel is shown.

| Signal Name: WSO_FL | | | | Pin Number: 23 | |
|--|-----|---------|-----|--|----------------|
| Schematic (vehicle side) | | | | Interface circuit (ECU side) | |
|  | | | |  | |
| Item | Min | Typ | Max | Unit | Remarks |
| Reference | | GND_ECU | | | |
| DC output current, I _{out} | | | 50m | A | |
| H voltage level, U _{out_high} | | | | V | Open collector |
| L voltage level, U _{out_low} | | | 1.5 | V | @ I ≤ 50mA |

3. Option Wheel Speed Interface

We developed a wheel speed signal splitter that duplicates the signal from the wheel speed sensor. This is useful for providing a DF11 signal to other systems in the car, which are also adapted to this signal type, such as specially adapted displays and data loggers. This is not intended to transmit signals to OEM controllers.

6 Included in the Kit

6.1 Parts Overview Kit 1

ABS M5 Kit 1 (F02U.V05.289-01) includes the following parts, which are also available as individual spare parts (Hydraulic unit only in exchange):

| Description | Part Number |
|---|--|
| Hydraulic unit DF11i | F02U.V05.286-01 |
| Hydraulic unit DF11S | F02U.V05.287-01 |
| Hydraulic unit DF11V | F02U.V05.288-01 |
| Mounting plate for Hydraulic unit | 0265.Y40.T56-02 |
| 2 brake pressure sensors PSS-260 | 0261.545.040 |
| 4 wheel speed sensors DF11S with production type connectors | 0265.008.022 (in combination with DF11S module) |
| Yaw/Acceleration sensor MM5.10 | 500 kbaud: F02U.V02.589-01 or 1 Mbaud: F02U.V02.590-01 (required for system combination with ECU MS 6 or MS 7) |
| Damping plate for MM5.10 | 1271.032.390 |
| 12-position ABS map switch | F02U.V03.390-01 |
| ABS M5 scale, standard (OFF on 12) | F02U.004.709-01 |
| ABS M5 scale, alternative (OFF on 1) | F02U.004.708-01 |
| ABS warning light LED (MIL) | F02U.V00.112-02 |
| Wiring harness with motorsport connectors, customer-specific layout, wheel speed sensors with production type connectors. | |

6.2 Parts Overview Kit 2

ABS M5 Kit 2 (F02U.V05.290-01) includes all parts of Kit 1 with the following differences:

| Description | Part Number |
|---|---|
| 4 wheel speed sensors DF11S with motorsport connectors | F02U.V00.534-02 (same sensor head as 0265.008.022) |
| Wiring harness with motorsport connectors, customer-specific layout | |

6.3 Parts Overview Clubsport

There are a few variants of the ABS M5 Clubsport available:

| Description | Part Number |
|--------------------------------------|-----------------|
| Kit Clubsport (500 kbaud, for DF11i) | F02U.V05.291-01 |
| Kit Clubsport (1 Mbaud, for DF11i) | F02U.V05.292-01 |
| Kit Clubsport (500 kbaud, DF11S) | F02U.V05.293-01 |
| Kit Clubsport (1 Mbaud, DF11S) | F02U.V05.294-01 |
| Kit Clubsport (500 kbaud, DF11V) | F02U.V05.295-01 |
| Kit Clubsport (1 Mbaud, DF11V) | F02U.V05.296-01 |

ABS M5 Clubsport includes all parts of Kit 1, but a different wiring harness, which cannot be modified. By default, the wiring harness includes a 60 Ohm terminal resistance, which can be replaced customer specific by a 120 Ohm or deleted completely, see Wiring Harness ABS M5 Clubsport [► 54].

| Description | Part Number |
|--------------------------|-----------------|
| Wiring harness Clubsport | F02U.V02.642-01 |

6.4 Connectors Overview Kit 1

ABS M5 Kit 1 includes the following connectors, which are also available as individual spare parts:

| Connector for | Part Number |
|---------------------------------------|-----------------|
| Control unit | |
| Departure on top | F02U.B00.238-01 |
| Departure on bottom | F02U.B00.237-01 |
| Brake pressure sensor | D261.205.335-01 |
| Compact 3-pin connector | |
| 12-position ABS map switch | F02U.000.230-01 |
| ASL006-05SE-HE | |
| ABS warning light (MIL) | F02U.000.226-01 |
| ASL006-05SA-HE | |
| Wheel speed sensor | F02U.B00.241-01 |
| Tyco 2-pin connector | |
| Yaw/acceleration sensor | F02U.B00.435-01 |
| Tyco 4-pin connector | |
| Diagnosis connector | F02U.000.258-01 |
| AS012-35SN | |
| Wheel speed signal splitter ABS-sided | F02U.000.443-01 |
| AS612-35SN | |
| Data-logger intersection | F02U.000.229-01 |
| ASL006-05SD-HE | |

6.5 Connectors Overview Kit 2

ABS M5 Kit 2 includes all connectors from Kit 1 with the following differences:

| Connector for | Part Number |
|---------------------------------------|-----------------|
| Wiring harness side ASL006-05PN-HE | F02U.000.342-01 |
| Sensor side ASL606-05SN-HE | F02U.000.416-01 |

6.6 Connectors Overview Clubsport

ABS M5 Kit Clubsport includes all connectors of Kit 1 with the following differences:

| Connector for | Part Number |
|---|-----------------|
| Encoding connector CAN harness-side Super Seal 2-pole | F02U.B00.246-01 |
| Encoding connector CAN with a 60 Ohm resistor Super Seal 2-pole | F02U.B00.247-01 |

7 Optional Accessories

7.1 MSA Box II

ABS M5 communicates with your laptop via the MSA Box II. It has a USB connection to the laptop and a motorsport connector to interface with the ABS M5 wiring harness. Communication via CAN.

| Description | Part Number |
|-------------|-----------------|
| MSA Box II | F02U.V00.327-03 |

7.2 Wheel Speed Signal Splitter

We developed a wheel speed signal splitter that duplicates the signal from the wheel speed sensor. This is useful for providing a DF11 signal to other systems in the car, which are also adapted to this signal type, such as specially adapted displays and data loggers. This is not intended to transmit signals to OEM controllers.

| Description | Part Number |
|---|-----------------|
| Wheel speed signal splitter with 1 motorsport connector | F02U.V00.335-03 |

See chapter Adaptations to your Vehicle [► 12] for further options to transmit the wheel speed signals to your vehicle.

7.3 Data Logger C 70

All ABS M5 data can be stored on a CAN-compatible data logger. We recommend to use our C 70 data logger for storing and analyzing ABS M5 data.

Bosch Motorsport provides a standardized CAN log in DBC format for analyzing recorded CAN data. A reduced version of the dbc-file could be found at our homepage www.bosch-motorsport.com.

| Description | Part Number |
|------------------|-----------------|
| Data Logger C 70 | F02U.V02.302-02 |

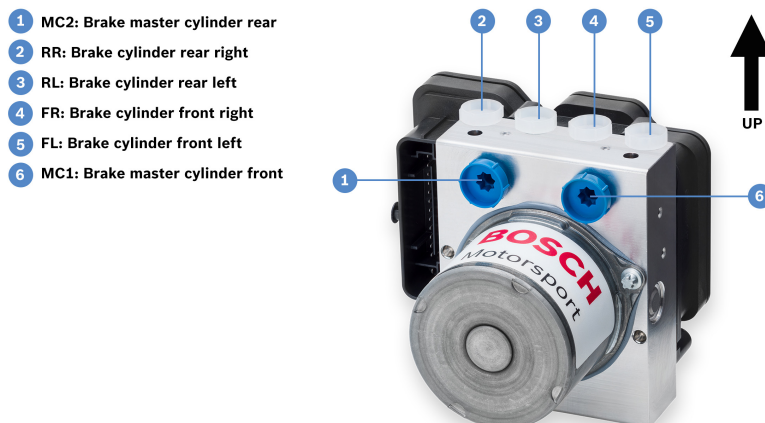
7.4 Displays DDU 10 and DDU 11

The DDU 10 and DDU 11 displays offer up to 8 GB of onboard data storage and can be used as a logger.

| Description | Part Number |
|----------------|-----------------|
| Display DDU 10 | F02U.V02.659-02 |
| Display DDU 10 | F02U.V03.208-03 |

8 Assembling the Parts

8.1 Hydraulic Power Unit with attached Control Unit



The hydraulic power unit with attached control unit has six hydraulic connections: two for the master cylinders (one for the front and one for the rear axle) and four for the brake cylinders.



CAUTION

The hydraulic power unit is prefilled with brake fluid. During assembly, make sure as little brake fluid as possible is lost.

When installing the hydraulic power unit, make sure the wheel brake line connections are facing upwards to ensure air can be bled out. Secure the hydraulic power unit to the assembly plate supplied with the ABS M5 using the M10x1 screw thread on the underside of the casing. To reduce vibration, rubber pads should be fitted between the assembly plate and the vehicle chassis. To allow easy connection of the main ABS ECU connector, maintain a 10 mm distance between the vehicle chassis and the bottom of the assembly plate.



NOTICE

Correct position for installation: wheel brake line connections should face upwards.

Install with rubber pads/blocks to reduce vibration.

Leave 10 mm or larger gap in between the vehicle chassis and bottom of assembly plate.

For more on assembly see Offer Drawing Hydraulic Unit [► 45].



NOTICE

Conform to FIA rules for GT3

With only 8 active hydraulic valves, the ABS M5 conforms to FIA rules regarding brake modulation hardware.

**NOTICE**

We recommend an exchange of the hydraulic power unit after one year.

In racing vehicles, hydraulic units are subjected to significantly higher loads than in production vehicles. We therefore recommend replacing them even when they are fully functional, to keep the residual risk of failure as low as possible.

8.2 Brake Pressure Sensor



Install the brake pressure sensors into the front and rear axle brake circuits between the master cylinders and the hydraulic power unit. The sensors are metric thread, M10x1. Before assembly, fill the sensors with brake fluid, e.g. with a small medical syringe. So the brake system can be fully bled, the measuring holes of the brake pressure sensors should point upwards.

**NOTICE**

The use of other than the supplied sensors will destroy the unit permanently. ABS M4 sensors are not compatible with ABS M5.

Install into the front and rear axle brake circuit between the master cylinder and the hydraulic power unit as far away from the ABS unit as possible to avoid damages due to vibration.

Fill sensor with brake fluid before installing.

For more on assembly see Offer Drawing Brake Pressure Sensor [► 47].

8.3 Wheel Speed Sensors



Bosch Motorsport ABS M5 needs specific wheel speed signals, which are supplied only from active speed sensors like e.g. from Bosch DF11-family. These double hall sensors operate on the differential principle. The ABS M5 needs all four speed sensors to function; otherwise the system assumes there is an error and shuts down. Therefore, you should exclusively use the speed sensors as supplied in the ABS M5-Kit (see section Offer Drawing Wheel Speed Sensor [► 46]). Existing wheel speed sensors can be tested and approved by us.

Pay attention to the polarity when you are connecting wheel speed sensors.

Install the sensor in the right direction, i.e. the encoder wheel and sensor must lie in the defined installation position (fixation screw in rotation position of the encoder wheel). The sensor will not work if you install it in a position other than the recommended installation

position. Make sure the sensor is mounted and secured as tight as possible to prevent sensor errors or failures from vibration. You can find the sensor's dimensions and how to install the sensor on Offer Drawing Wheel Speed Sensor [► 46].

**NOTICE**

Use only differential sensors, like Bosch DF11 or similar. Supported sensors: DF11i, DF11S and DF11V.

Securely mount sensors and pay attention to correct mounting position (sensors direction sensitive). Choose sensor mounts that are as still as possible. Sensor dimensions and mounting requirements can be found in the Offer Drawing Wheel Speed Sensor [► 46].

8.4 Encoder Wheel

Encoder wheels usually have 48 teeth. The tooth/gap ratio should be 50 % and the teeth should be 3 mm in height. The encoder wheel must be made of a ferromagnetic material. If required, Bosch Motorsport can provide technical documentation on positioning the encoder wheel. See the back cover of this booklet for our contact information.

8.5 Distance between the Sensor and the Encoder Wheel

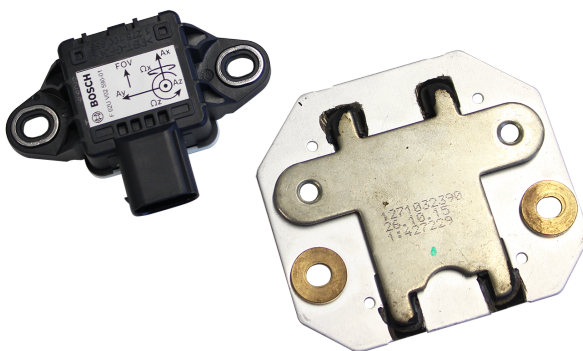
You can adjust the distance between the sensor and the encoder wheel to fit the encoder wheel's dimensions and other installation conditions, but gap is normally between 0.8 ± 0.1 mm.

**NOTICE**

Use a ferromagnetic incremental wheel.
Leave a 0.8 ± 0.1 mm gap between sensor and encoder wheel.

For more on assembly see Offer Drawing Wheel Speed Sensor [► 46].

8.6 Yaw/Acceleration Sensor



ABS M5 uses a yaw rate sensor from the MM5.10 generation with CAN speeds of 500 kBaud or 1 MBaud. The yaw/acceleration sensor is specific to the system and should be mounted as close as possible to the center of gravity of the vehicle. The sensor should be assembled with the supplied damping plate. Position the sensor so that the connector is pointing towards the rear of the vehicle.



NOTICE

For system combination with ECU MS 6 or MS 7, the 1 MBaud sensor is required.

The ABS system will not work if you choose any alternative yaw rate sensor.



NOTICE

Only use the provided kit sensor.

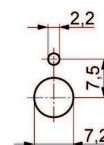
Use the damping plate.

Make sure the sensor is facing the correct direction see image above.

8.7 Map Switch



Max. tightening torque:
1-2 Nm!



Front-panel cut out with locating lug

While driving, the driver can use the map switch to select different control settings and find the optimum setting for his/her driving style. For this reason, make sure the switch is mounted within reach of the driver. Many have found it helpful to fit a diagram showing the current switch position, see also Features [► 6], diagram in chapter. The switch position is also broadcast on the CAN Bus so it can be displayed with a dash (e.g. the DDU 9 and DDU 10 from Bosch Motorsport).



NOTICE

Only use the supplied Map Switch.

Do not exceed the max. tightening torque of 1 to 2 Nm. Over-torquing can damage the switch or make it difficult to turn.

Remove the front cover of the switch to access the retaining hardware.

8.8 Warning Light (MIL)



LED



Front-panel cut

The included wiring harness is structured in such a way that the power supply to the warning light (MIL) is branched off before the main switch for ABS M5 (terminal 30). This is the only way to ensure that the warning light (MIL) is lit when ABS M5 is not working.

Cable length connector to electronic board: 600 mm



NOTICE

The MIL will stay illuminated in the following cases:

Map switch is in the OFF position

The user is connected to the car via the RaceABS tool and MSA Box

There is an active fault disabling ABS M5

8.9 Brake Lines

All hydraulic connections between ABS M5 Use rigid steel brake lines with a diameter of 3.3 mm for as much of the plumbing as possible. Flexible line should be kept to an absolute minimum for optimal brake control and pedal feel.

The ABS M5 units use a DIN (bubble) flare convention common to European OEM applications. The best and simplest way to adapt the system hydraulically is with an M12x1 DIN tube nut on the ports. Tube nut size should be fitting to the hard line size used. Adapters should be avoided if possible.

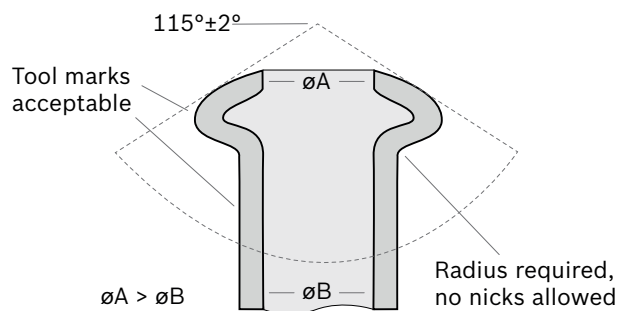


Illustration 1:

The EBS unit is secured in the vehicle on the provided mounting board. During operation, the EBS unit will vibrate. These vibrations are then transferred to the brake lines. To prevent vibration-induced damage to the brake lines, they must not be secured at a distance of up to 20 cm from the EBS unit so that they can vibrate freely.



NOTICE

We recommend using rigid metal brake lines; use flexible lines only at points where they are necessary.

Do not secure brake lines 0 to 20 cm from the EBS unit. The unit vibrates and would cause risk of damage to the lines.

Use brake lines with a minimum inside diameter of 3.2 mm.

8.10 Brake Calipers

Use brake calipers that are as stiff as possible. Any flex in the brake caliper causes extra fluid volume that must be regulated by the ABS M5, which reduces performance.

During ABS M5 operation there will be a significantly higher load on the brake piston seals. For this reason, brake piston seals will require more frequent monitoring.

**NOTICE**

**Monitor brake piston seals more often.
Use brake calipers that are as stiff as possible.**

The higher the brake pressure is, the larger is the elasticity of the brake. A locking pressure of max. 80 bar is optimal.

8.11 Master Cylinders

The master cylinders in a race car equipped with ABS are heavily exposed to piston vibrations due to ABS return fluid pump.

Test and inspect the master cylinders frequently, both to ensure safety as well as to avoid damage to the ABS unit.

**CAUTION**

Test and inspect the master cylinder frequently.

8.12 Pressure Medium

Brake components and systems are designed for exclusive use with the following glycol/glycol ether-based brake fluids, including their mixtures:

- DOT 4 (including SAE/ISO/JIS sub-classes)
- DOT 5.1

according to

- FMVSS 116, Issue 16.10.2015
- SAE J 1703, Issue 28.08.2014
- SAE J 1704, Issue 28.08.2014
- DIN ISO 4925, Issue 05.02.2014
- JIS K2233, Issue 20.06.2006

In general, brake components and systems are designed to operate with these generic brake fluid categories. However, brake fluid characteristics impact performance and reliability.

For use in motor racing, some manufacturers offer fluids with a boiling point of over 300°C. These are highly hygroscopic and therefore should be replaced more often than usual. Please follow the brake fluid manufacturer's recommendations regarding testing and changing.

9 Laptop Communication

The MSA-Box II from Bosch Motorsport is the communication interface between ABS M5 and the programming and diagnostic software on your laptop. The MSA-Box II has two connectors: a USB connector for connection to the laptop and a motor sports connector for connection to the mating connector in the vehicle wiring harness.



Installing the MSA-Box II driver:

Before using the MSA-Box II for the first time, you need to install a specific driver on your laptop. Find the driver for free download on our website www.bosch-motorsport.com.



NOTICE

Please make sure that the MSA-Box II is not connected to the laptop while you are installing the driver.

Connect the MSA-Box II to the laptop after installing the driver. This will trigger the initial communication between the laptop and the MSA-Box II. Follow any prompts that may follow to install the MSA-Box II. Once you complete any prompts and computer recognizes the MSA-Box II, the MSA-Box II is ready for use.

Steps:

1. Unplug the MSA-Box II from the laptop.
2. Install the driver.
3. Plug the MSA-Box II into the laptop.

You can connect ABS M5 to a laptop with the MSA-Box II via the "diagnosis interface" connector. The diagnosis interface connector should be placed so it is easily accessible. You can use programming and diagnosis software, see section Programming and Diagnosis Software [► 25], to program settings specific to the vehicle and open/delete error messages.

10 Programming and Diagnosis Software

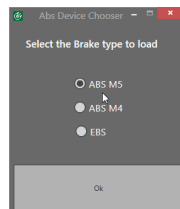
10.1 Installing the Programming and Diagnosis Software

After installing the MSA-Box II you need to install the programming and diagnostic software RaceABS. You can find the software for free download on our website: www.bosch-motorsport.com

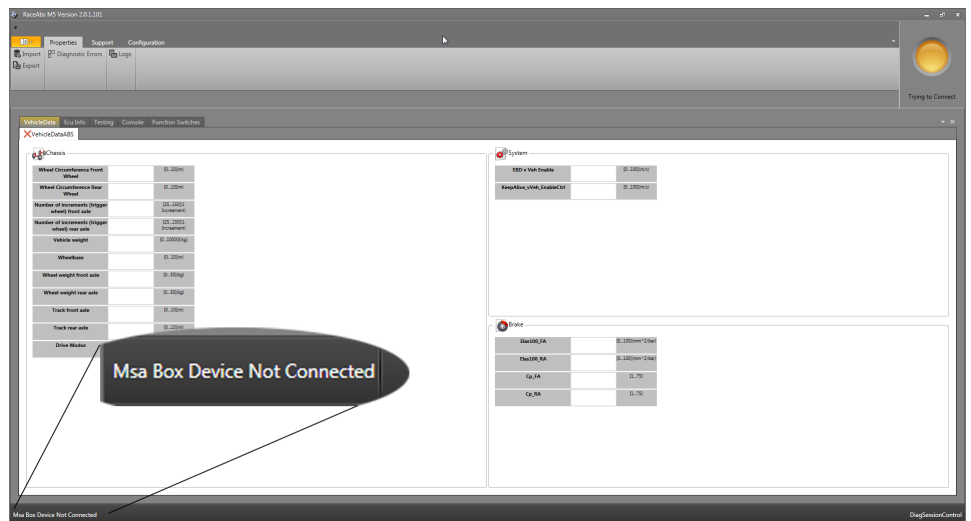
Switch on the ignition

Plug the MSA-Box's USB connector into your laptop and its motorsport connector into the ABS M5 wire harness diagnostic interface to enable communication.

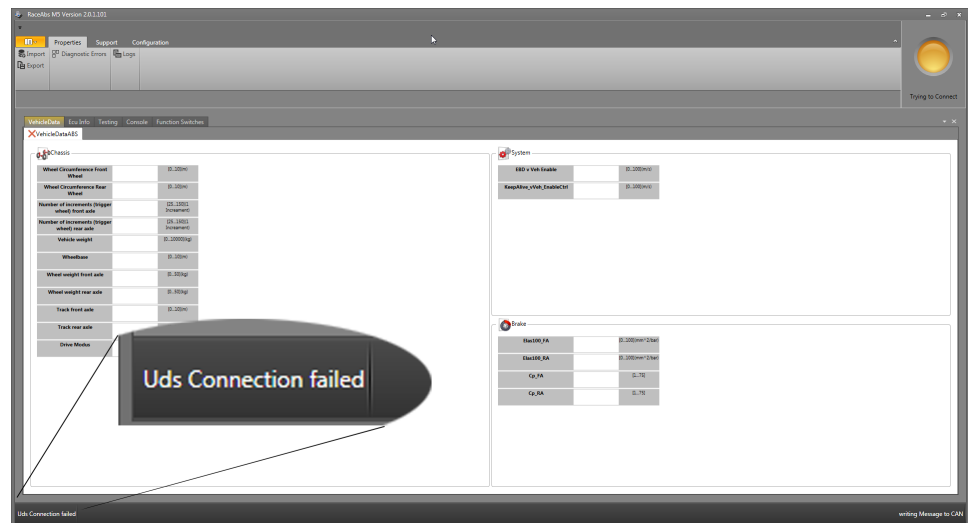
The installation creates a shortcut on your desktop to the RaceABS software. Click it to start the application. A green status indicator shows when the connection is successful. A window pops up where you can select your brake version to load.



If you try to launch the software without the MSA-Box II to laptop connection, the status indicator in Explorer lights red / yellow and an error message appears in the status bar:



The following message pops up when either the ABS M5-ECU gets no power supply (e.g. ignition OFF) or the MSA-Box II is not connected to the wiring harness. Please make sure that the connection between the diagnosis software and MSA-Box II is assured:



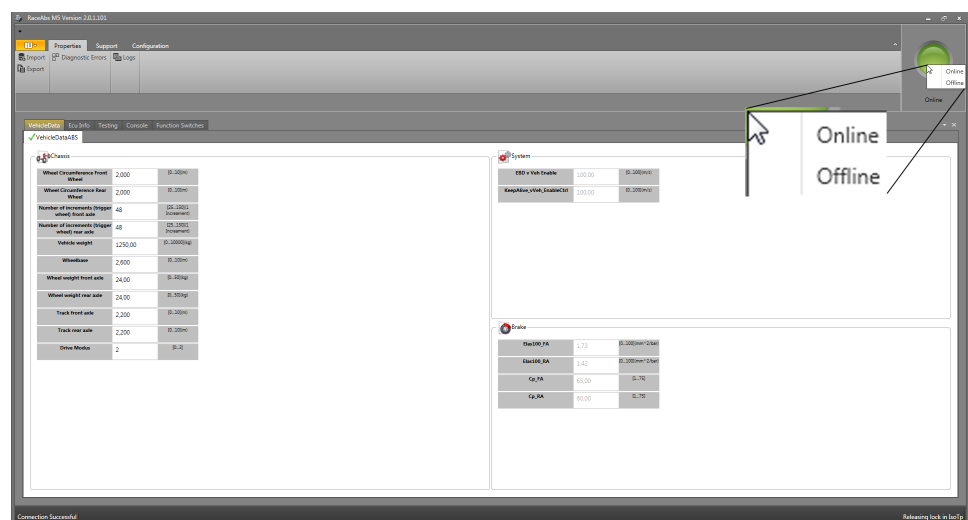
Colors of the status indicator

The status indicator can shine in the following colors:

| | |
|---------------------------|--|
| Red | No connection |
| Yellow | Connection in progress or MSA-Box II cannot create a connection with the ABS M5 (e.g. ABS M5 switched off) |
| Green | Connection successful, Online mode |
| White | Offline mode |
| Red / Yellow low flashing | MSA-Box II is not connected to the laptop |

Change between Online and Offline Mode

If a connection does not exist, it is easier to operate with the diagnosis software in offline mode. Please click with the right mouse button on the green status indicator to choose between online and offline mode:



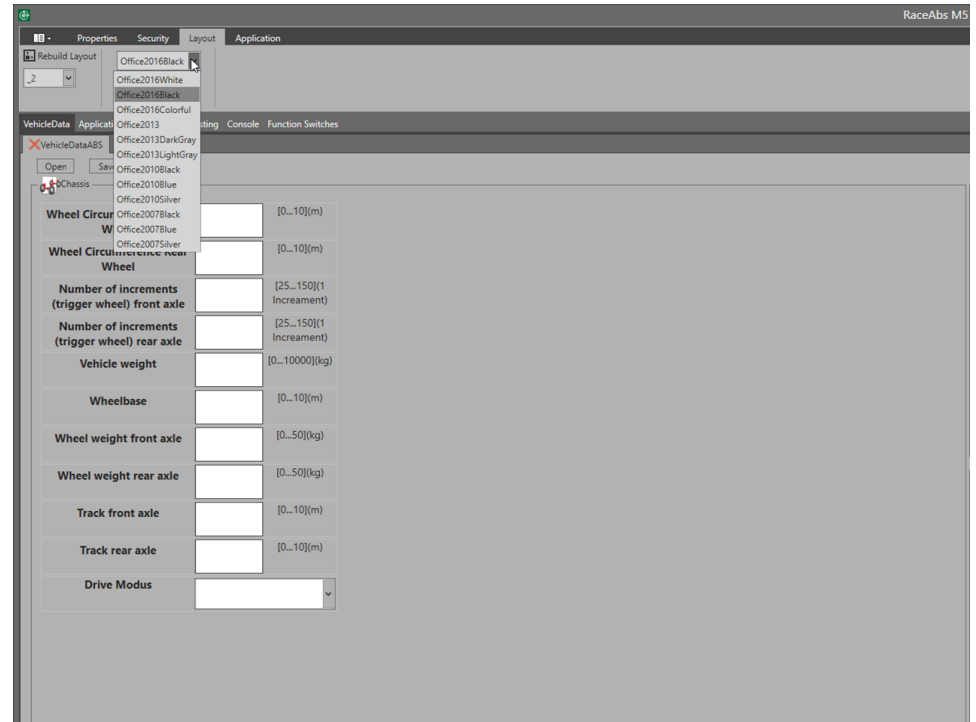
A green status indicator signalizes the online mode; a white status indicator signalizes the offline mode.



NOTICE

You can only change the status when the ABS M5 tree is closed.

Custom Theme Selection



Selection of Custom Themes / Skin is now possible in RaceABS. This helps the customer to configure the Tool as per his requirements.

10.2 Features of the Programming and Diagnosis Software

10.2.1 Diagnostic Code

The ABS M5-ECU sends the stored errors as coded data to RaceABS. These codes are then translated by a translation file and displayed on the page "Ecu Info" in RaceABS as plain text.

After installation of RaceABS, a default file will be used for the translation. If you don't see plain text or if there is an orange colored warning, you do not have the matching translation file to your software. With a not matching file, some codes cannot be translated or might be translated in the wrong way. Therefore it is important to use the correct translation file.

To get the correct translation file, please conduct the following steps:

- Check on the top of the “ECU Info” page which software number and software version is used in your ABS M5.
- Go to the Bosch Motorsport homepage and download the matching diagnostic translation file to your software. You will find in the naming of the diagnostic translation file the software number as BB number and the version as a V number, zeros at the end might be skipped in the naming. The numbers of the file need to match the numbers of the software. The file is an .XML file.
 - For example if your ABS M5 runs on the software 96242 and the version 03.00.00.00.00.00. You will need the file TKWINX_FAILUREMEMORYDESCRIPTION_BB96242_V0300.XML
- Store the file on your computer.
- Click in RaceABS on “Properties” - “Diagnostic Errors” and select the matching diagnostic translation file.

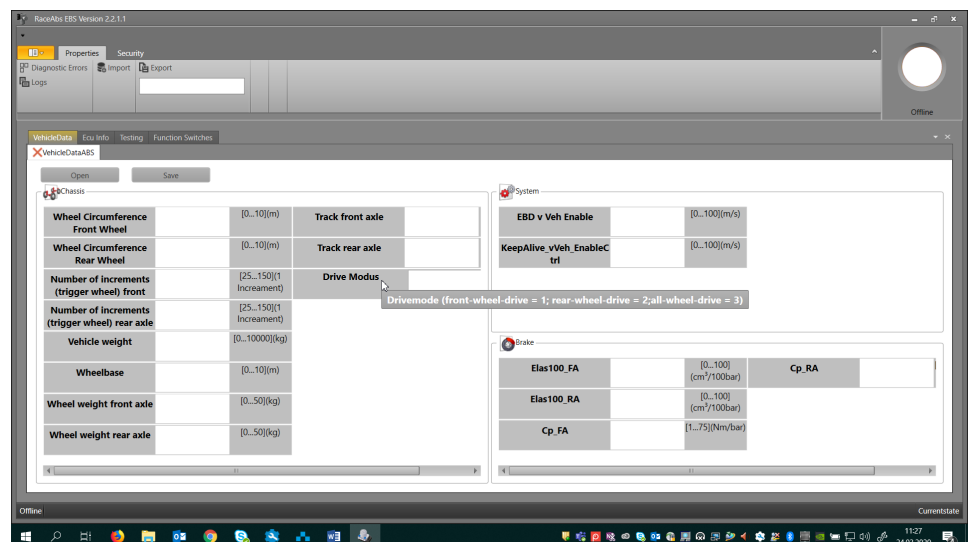
You will find the most common translation files on our homepage. If your needed file is missing, please contact your dealer or the OEM customer service.

10.2.2 Vehicle Data

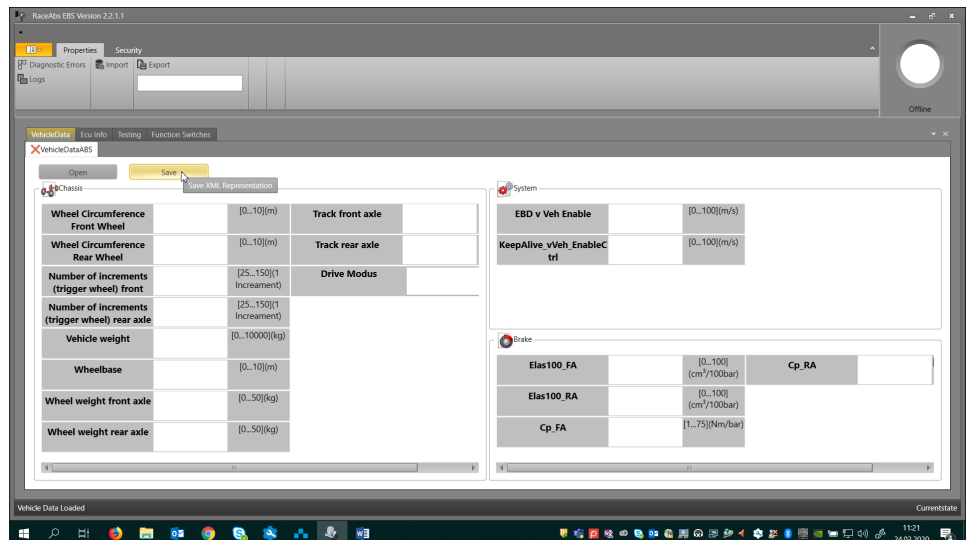
You can find a form to fill in your vehicle data on www.bosch-motorsport.com. This form should be provided to you by your dealer with the order of the kit, if the kit shall be programmed by Bosch.

If you need to replace the ECU or modify the programmed vehicle data, you can update the data in the software by yourself.

Within the window “Vehicle Data ABS M5”, a short declaration or the measuring unit for each value can be shown. By holding the cursor over a data range, a small window with the declaration occurs.



You can save and open the vehicle data of the window “Vehicle Data ABS M5” separately. Therefore, click the SAVE button.

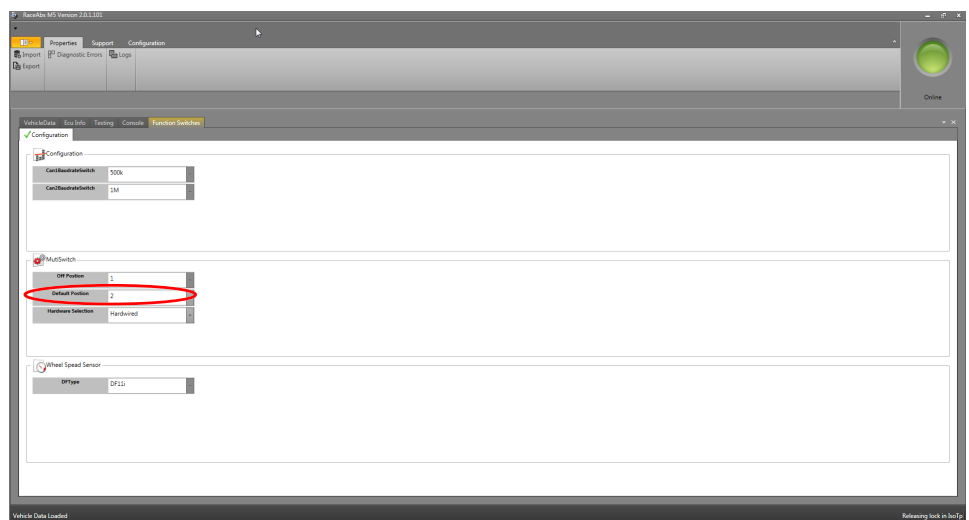


NOTICE

Only the active window will be saved.

Default value for the map switch

For the 12-position map switch, you can specify a default value. If the function switch fails for any reason, the switch automatically takes the position of the default value. To assign a position for the default value, select a number between one and twelve under "MultiSwitch" in the field "Default Position":



NOTICE

You may want to be strategic about how you make this setting, for example, making it the best compromise position for all conditions.

10.2.3 Testing

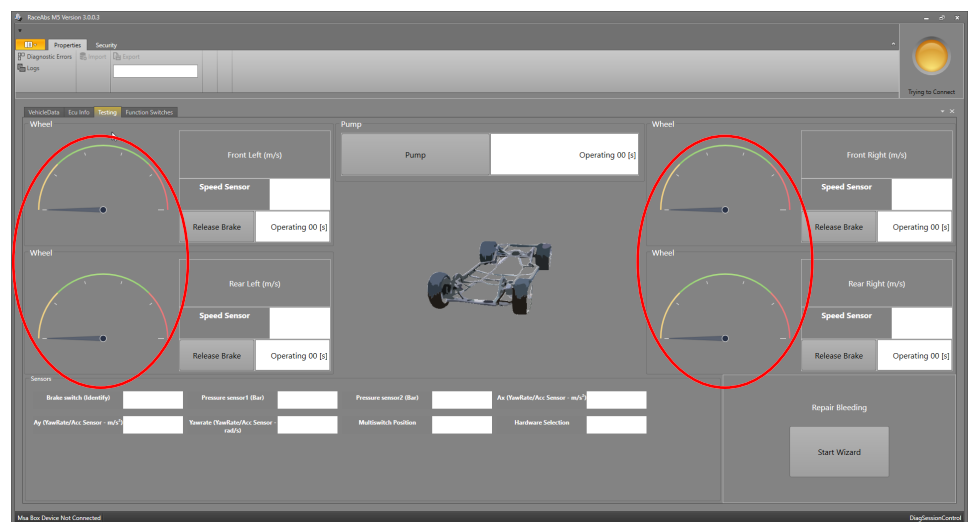
After assembling the system components, you need to carry out a function test before the first test drive. This test will ensure all components (electrical and hydraulic) were assembled correctly and are functioning properly. The vehicle should be placed on four jack stands or on a hoist so that all four wheels can be moved freely. If there is no other option, you can lift and test each wheel separately. You will need an assistant to help you check the hydraulic allocation of the wheels.

Step 1: Testing the communication with the ABS M5 ECU

See section Laptop Communication [► 24].

Step 2: Testing the wheel speed allocations

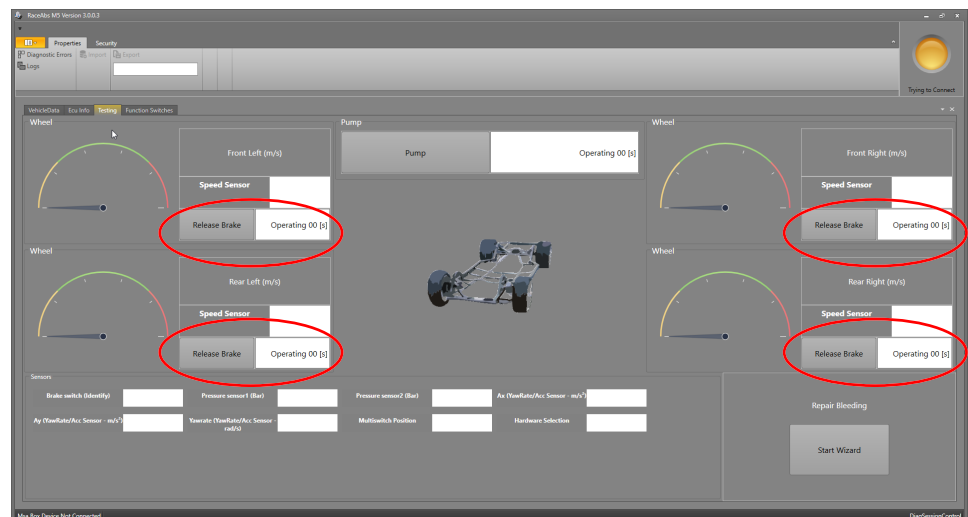
With the vehicle jacked up, spin individually all four wheels clockwise and check for the proper front/back, left/right allocation. When you spin each wheel, the corresponding position should show a value in the RaceABS software under the "Testing" tab:



You just do this to see if a signal is received by the ABS M5 unit. This is not a signal quality check.

Step 3: Testing the hydraulic allocations

Have an assistant apply the brake pedal and maintain the brake pressure so all four wheels of the jacked up vehicle are locked. Therefore, a brake pressure of 15 to 20 bar is sufficient. Unlock each wheel successively by clicking on "Release Brake". The selected wheel should run free now.



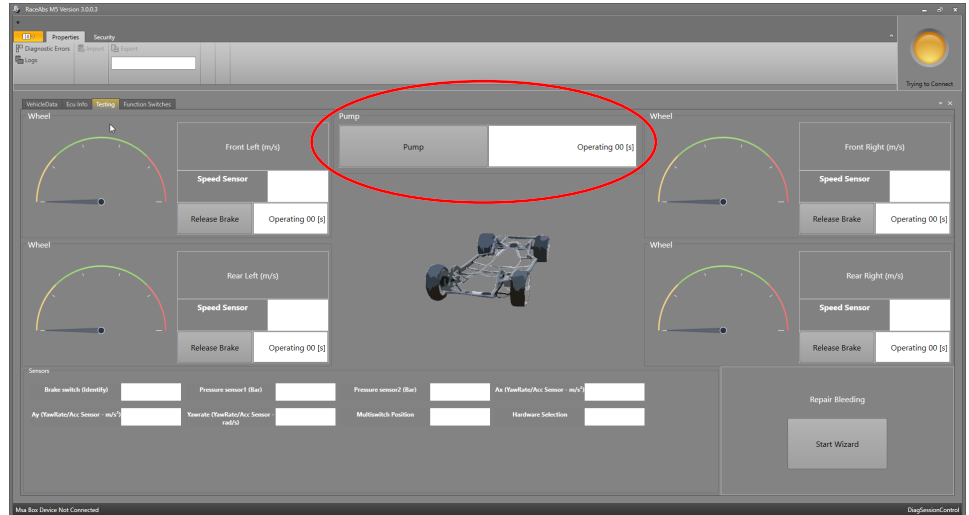


NOTICE

Certain vehicles require a high torque input at the wheel to overcome the effect of residual brake pressure and resulting torque.

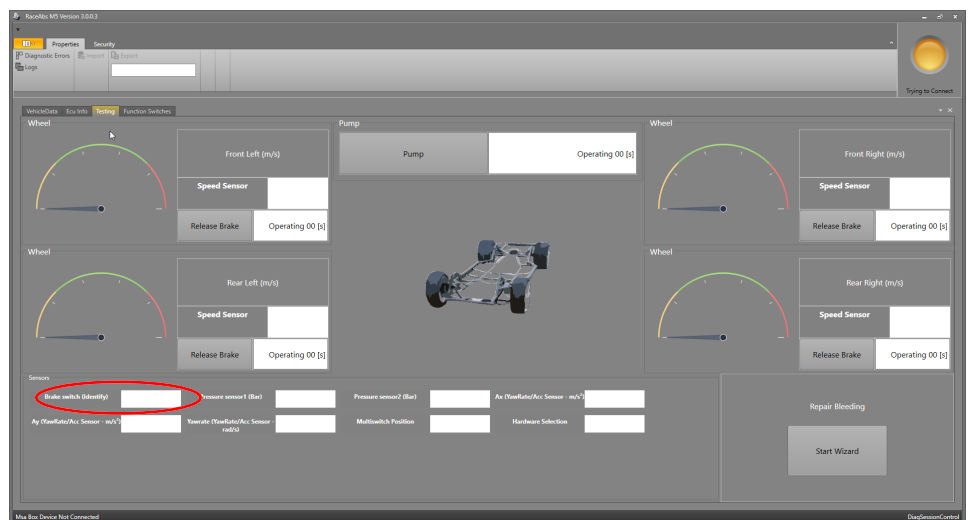
Step 4: Testing the electrical pump motor

If you click the "Pump" button, the pump motor should run for 10 seconds or till you click the button again.



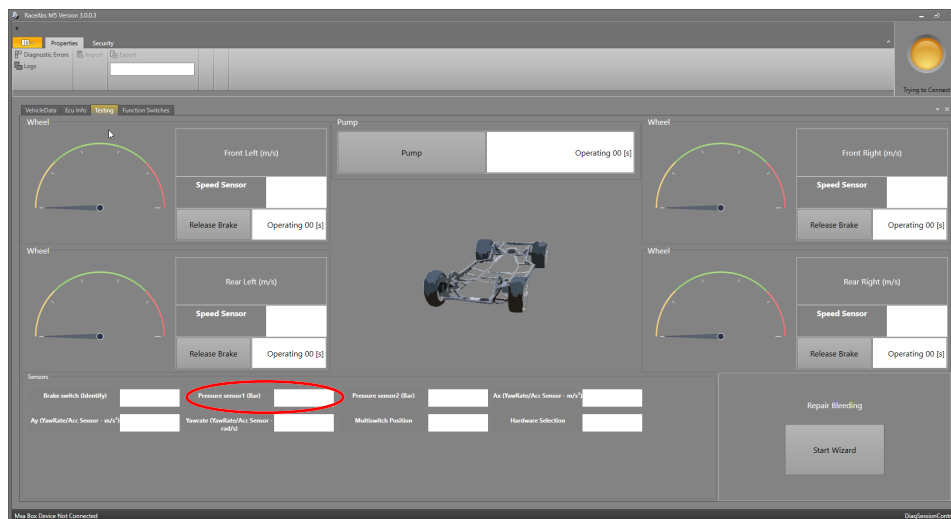
Step 5: Testing the function of the brake pressure sensor and brake light switch

Start the RaceABS with connection to the MSA-Box II and press the brake pedal for a few seconds with slowly rising pressure. The digital display "Brake switch" bit should toggle from 0 to 1, see screenshot below.



If the bit does not toggle, check the pressure sensors. The brake light switch bls is a function of the pressure sensors.

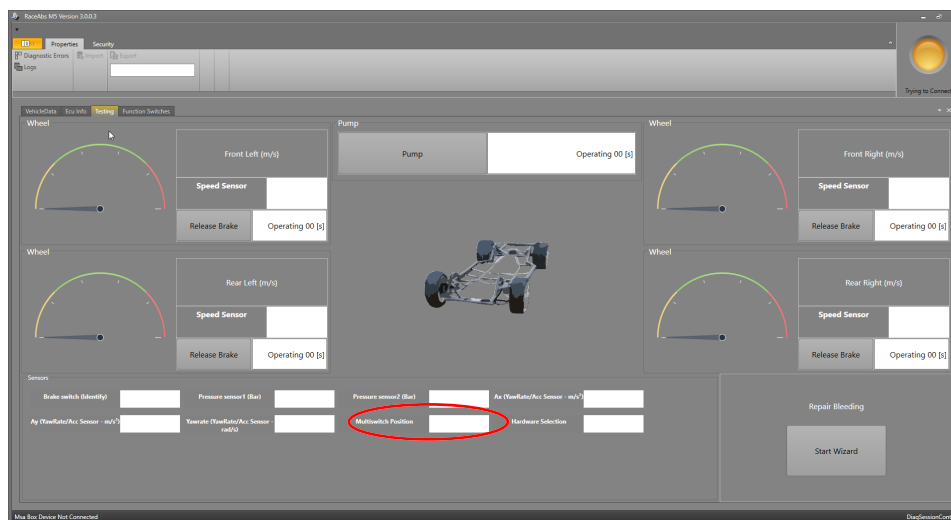
The digital display „Pressure sensor“ should show a logical value, e.g. 3.87, in the screenshot below.



If the software displays no value or an illogical value, open the “ECU Info” tab and check the error memory. Do you find errors relating to the brake pressure sensor? See section ECU Info (Diagnostics) ► 34] for more information regarding ECU diagnostic errors.

Step 6: Testing the function of the map switch

Turn the 12-position map switch through full rotation. With every step, the number of measuring points should increase by 1.



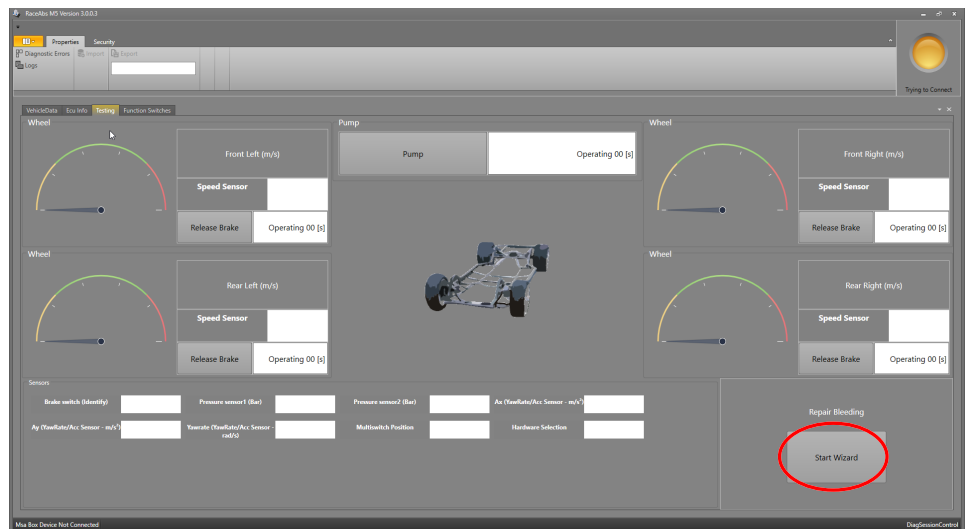
NOTICE

MIL shines permanently in diagnosis mode.

10.2.4 Repair Bleeding Wizard

Under the “Testing” tab of the RaceABS software you will also find an area at the bottom right, labeled “Repair Bleeding” with the button “Start Wizard”. With this button, you will be guided through the bleed of the ABS M5 unit. This might be required if air might got trapped in the accumulator of the ABS M5 unit. It is recommended to perform the ABS M5 unit bleed after installation or if air got trapped in the brake lines and might got caught in the ABS M5 unit.

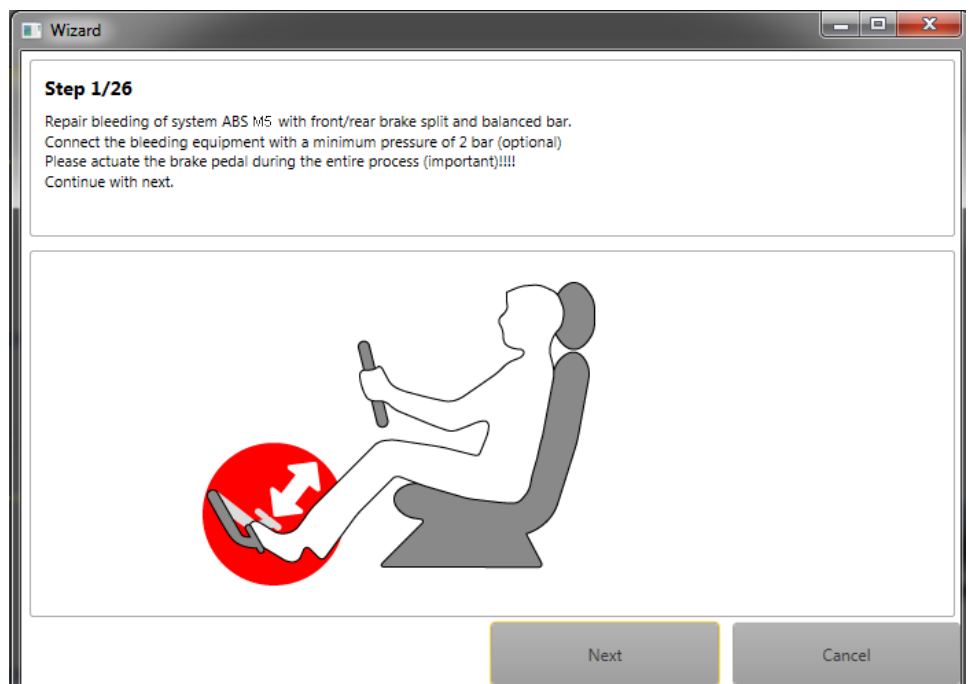
Click on the button “Start Wizard”, a new window will open and lead you step by step through the instruction for bleeding the ABS M5 unit. You will need three people to conduct the instruction.

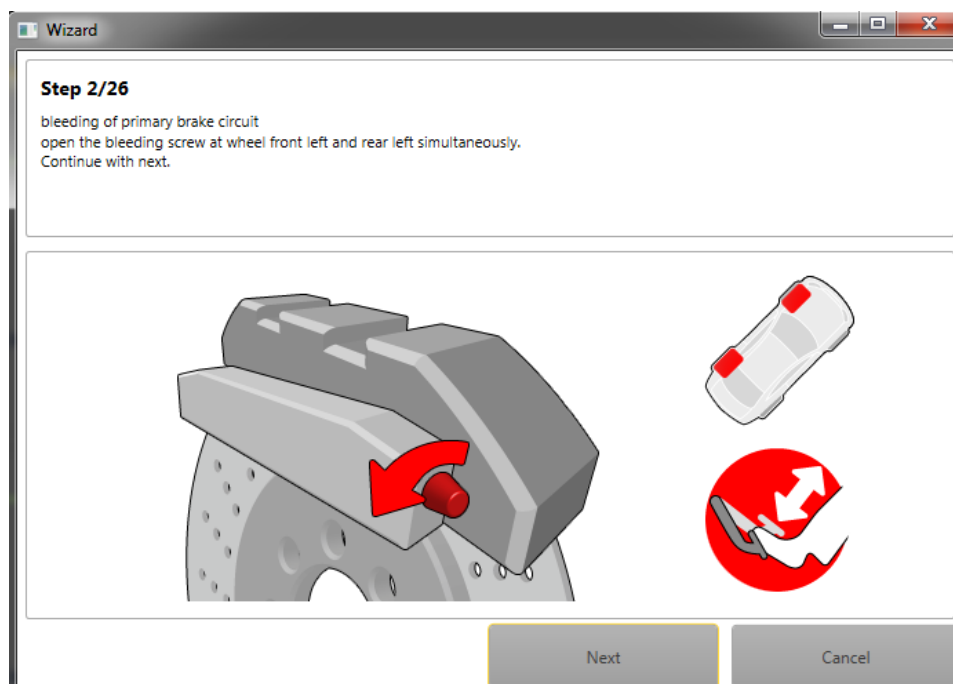


NOTICE

The Bleeding Wizard is only for bleeding the ABS M5 hydraulic power unit. The Bleeding Wizard is NOT to be used or substituted for bleeding the other parts of the brake system, like lines and brake cylinders. Make sure to bleed these other hydraulic parts of the brake system before and after bleeding the hydraulic unit with the Repair Bleeding Wizard.

During the ABS M5 bleeding process the brake pedal should be actuated continuously except when opening or closing brake bleeder valves.



**NOTICE**

For vehicles with brake balance bar, please open one front and one rear bleeder valve for proper function of the balance bar during the bleeding routine procedure.

10.2.5 ECU Info (Diagnostics)

Indication lamp

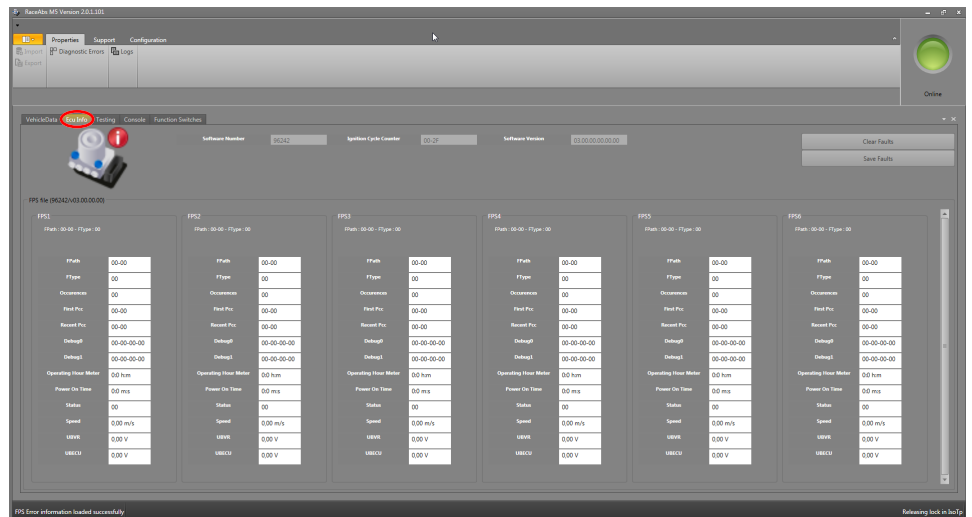
When you turn on the ignition or the ABS M5, the warning light (MIL) comes on briefly and then turns off again. This indicates the light's self-testing process. If the warning light (MIL) does NOT light up when you turn on the ignition or the ABS M5, you must establish the reason for this before taking any further action or before driving the vehicle.

**NOTICE**

The MIL will stay illuminated as long as the diagnostic tool is switched on.

Error log

If the warning light (MIL) is illuminated PERMANENTLY when you turn on the ignition or the ABS M5, or while driving, there is a system error. Extract the system's internal error log to analyze the error. You can access the log by clicking on the "ECU Info" tab in the RaceABS software.



NOTICE

Multi switch = Map switch



NOTICE

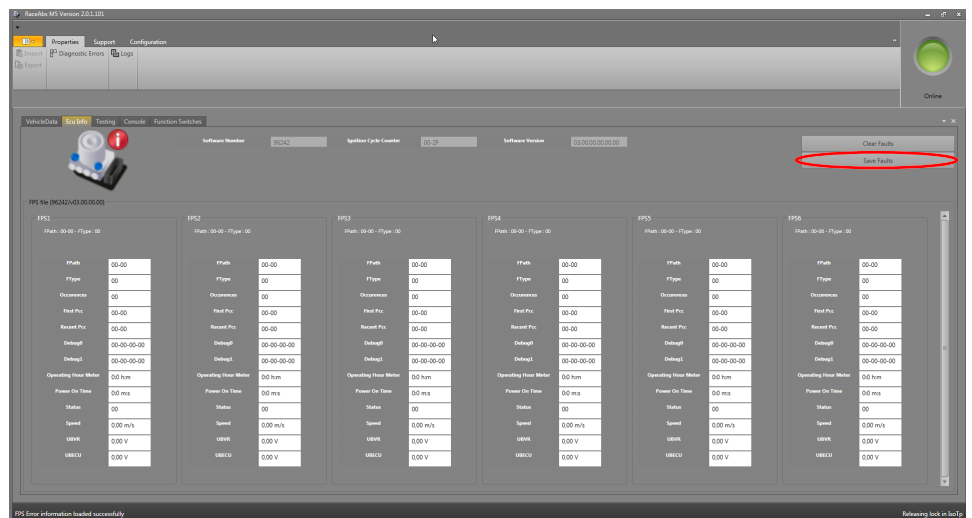
System reset after drive cycle faults.

Drive cycle faults, e.g. because of wheel speed sensor bug, need an ABS M5-ECU reset (Power off - Power on). After the reset, the car has to accelerate to more than 12 km/h for system check.

Save error log entries

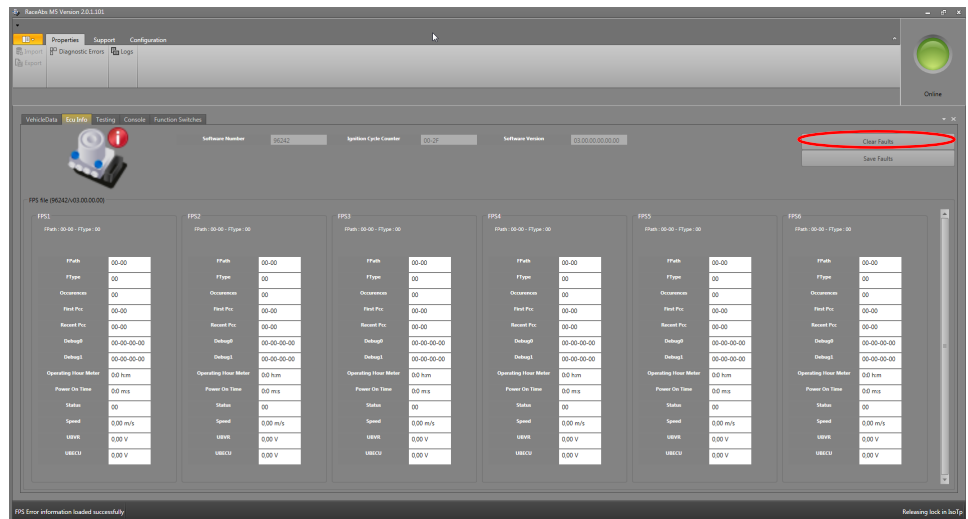
If any error log entries occur which are not listed above, please contact your dealer or the OEM customer service. Communication would be easier if you also send a copy of your error log entries.

Click on the right button named "Save Faults" to get a copy of the error log entry.



Delete error log entries

After carrying out the problem-solving actions, delete the entry from the error log by clicking on the “Clear Faults” button, as seen below:



Then turn ABS M5 off and on again. After you deactivated the software, the indication lamp will no longer glow.



NOTICE

If the faults are not all clearly described or if there is no error description, please check if you used the correct FPS-File or contact Bosch Motorsport for update.

Ignition Cycle Counter

The ignition cycle counter shows how often you switched on the ignition. If you compare the values of the ignition cycle counter and ICC at Failure Occurrence you can trace back at what time the faults occurred. If both fields show the same values, it is an actual fault.

11 Startup Checklist

This short checklist is intended to supplement the ABS M5's manual, not replace it. Prior to using this checklist, the user/installer should read the ABS M5 manual, especially section Laptop Communication [► 24] to Assembling the Parts [► 18].

Basics

- Hydraulic unit with attached control unit mounted correctly (mounting plate used, brake lines facing upwards), see section Hydraulic Power Unit with attached Control Unit [► 18].
- Brake pressure sensor and Yaw/Acceleration sensor installed in proper locations? See section Brake Pressure Sensor [► 19] and Yaw/Acceleration Sensor [► 20].
- Everything plugged in to harness, power ring terminals connected to battery, ground ring terminals connected to solid and clean chassis ground, circuit breakers installed properly, map switch turns off system. See section Brake Pressure Sensor [► 19] and Yaw/Acceleration Sensor [► 20].

Software Tool and Error Checking

- Connect to the ABS M5 control unit with MSA-Box II using RaceABS Software and ensure that all vehicle data has been entered correctly. The vehicle data can be saved and or loaded by right clicking in the screen.



NOTICE

Once the diagnosis software RaceABS is connected to the harness, the warning light (MIL) will light up and remain lit until it is disconnected. See section Testing [► 30], Step 2. If the MSA-Box II is not connected to the laptop, the indication lamp illuminates yellow.

- With the system on, switch to the "ECU Info" page and clear errors with clicking on Clear FPS. Wait a moment (system will self-refresh error stack). Reset the system by switching off/on. Check if any errors reappear in the error stack. If errors reappear, diagnose errors before proceeding. If anything was unplugged during the diagnostic process, errors will be present and need to be removed from the error stack. Next, cycle ABS M5 on/off switch and verify no errors are present after cycling power, see section ECU Info (Diagnostics) [► 34].

Error Notes

- In case of use of a wheel speed signal splitter: If the wheel speed signal splitter is disconnected, all four wheel speed sensors will have error entries.

Function Check

- While connected with the RaceABS software switch to the "Testing" page. Check all sensors for plausibility and proper function. Delete the balance bars. Press brake pedal: brake switch bit should toggle between 0 and 1, the display "Pressure sensor" should show a logical value. Check sensor and balance bar, if the brake switch doesn't toggle. Rotate map switch, the value "Multiswitch" should turn up clockwise. Manually move yaw/accelerometer sensor to the right and left as well as to the front and rear. The "Ax" and "Ay"-values should increase positive or negative analogue to the Tilt. See section Testing [► 30].

- Put the car on jack stands so all wheels can be freely rotated. While connected with the RaceABS software and viewing the "Testing" page, rotate each wheel and verify the correct wheel speed responds in the "Testing" page, see section Testing [► 30].
- Click "Pump On" button on the "Testing"-page. The pump now runs for 10 seconds or until you press the button again. After the pump shuts off, an assistant hold the brake pedal down (Please check: all wheels have to be locked!) Next, while the assistant still holds brake pedal down, click the "Release Brake" button for a given wheel (one at a time). Verify that brake releases at that wheel by rotating the wheel before clicking the next button. Repeat for each wheel.

**NOTICE**

**During this release test, the pump may switch on repetitively.
See chapter: Testing [► 30]**

- Click on the button "Start wizard" at the bottom right. Follow the instructions listed in the sub window in order to bleed the ABS M5 hydraulic unit.

**NOTICE**

**This will bleed the ABS M5 hydraulic unit only, not the brake lines or the wheel brake cylinders.
See chapter: Repair Bleeding Wizard [► 32]**

- Bleed brakes in normal fashion, starting with the furthest brake from the master cylinder and finishing with the nearest. Check errors one last time, diagnosis any errors present, then disconnect MSA-Box II from ABS M5 harness. Once MSA-Box II is disconnected verify that MIL lamp turns off and stays off.
- Check for proper brake operation at low speeds first. Start with map switch in a neutral position (position 5 to 7).

**NOTICE**

Refer to manual for more information regarding the map switch position function.

- Warning light (MIL) on for a short time when you switch on the ignition, on permanent when map switch in position 12 (OFF).

12 Legal

12.1 Legal Restrictions of Sale

The sale of this product in Mexico is prohibited.

Due to embargo restrictions, sale of this product in Russia, Belarus, Iran, Syria, and North Korea is prohibited.

13 CAN Protocol V19 customer from 0700 onwards

| | | | | | | | | | | | | |
|------------------------------|-------|-------------|--------------|------------|------------|---------------|------------|---------|---------|---------|------|---|
| ABS-MS CAN | | Version 19 | 11.12.2018 | | | | | | | | | |
| Customer version | | | | | | | | | | | | |
| | | | | | | | | | | | | |
| Input | | | | | | | | | | | | |
| Name | ID | Start [Bit] | Length [Bit] | Byte Order | Value Type | Initial Value | Factor | Offset | Minimum | Maximum | Unit | Comment |
| ABS_Switchposition | 0x24C | 0 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 11 | | Channel to send the switch position via CAN to the ABS. |
| Rate must be 10 ms / 100 Hz. | | | | | | | | | | | | |
| | | | | | | | | | | | | |
| ABS | | | | | | | | | | | | |
| Name | ID | Start [Bit] | Length [Bit] | Byte Order | Value Type | Initial Value | Factor | Offset | Minimum | Maximum | Unit | Comment |
| RG_VL_Bremse2 | 0x24A | 0 | 16 | Intel | Unsigned | 0 | 0.015625 | 0 | 0 | 100 | m/s | Wheel speed direct FL |
| RG_VR_Bremse2 | 0x24A | 16 | 16 | Intel | Unsigned | 0 | 0.015625 | 0 | 0 | 100 | m/s | Wheel speed direct FR |
| RG_HL_Bremse2 | 0x24A | 32 | 16 | Intel | Unsigned | 0 | 0.015625 | 0 | 0 | 100 | m/s | Wheel speed direct RL |
| RG_HR_Bremse2 | 0x24A | 48 | 16 | Intel | Unsigned | 0 | 0.015625 | 0 | 0 | 100 | m/s | Wheel speed direct RR |
| acc_FA | 0x342 | 0 | 8 | Intel | Unsigned | 0 | 0.05 | 0 | 0 | 10 | cm3 | Fill level of the fluid reservoir of the front axle. |
| acc_RA | 0x342 | 8 | 8 | Intel | Unsigned | 0 | 0.05 | 0 | 0 | 10 | cm3 | Fill level of the fluid reservoir of the rear axle. |
| WheelQuality_FL | 0x342 | 32 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 32 | | Identification bit for wheel sped signal disturbances, check the sensor and the surrounding if bit is >1. |
| WheelQuality_FR | 0x342 | 40 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 32 | | |
| WheelQuality_RL | 0x342 | 48 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 32 | | |
| WheelQuality_RR | 0x342 | 56 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 32 | | |
| Brake_bal_at50 | 0x560 | 16 | 16 | Intel | Unsigned | 0 | 0.1 | 0 | 0 | 100 | Bar | Calculated rear axle brake pressure if the front pressure is at 50 bar. |
| Brake_bal_at50_advice | 0x560 | 32 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 100 | Bar | Recommended rear axle brake pressure if the front pressure is at 50 bar. |
| Brake_bal_pct | 0x560 | 40 | 16 | Intel | Unsigned | 0 | 0.1 | 0 | 0 | 100 | % | Percental brake balance on the front axle. |
| Brake_bal_pct_advice | 0x560 | 56 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 100 | % | Recommended percental brake balance on the front axle. |
| AX1_ABS_int | 0x541 | 0 | 16 | Intel | Unsigned | 0 | 0.00012742 | -41.768 | -41.768 | 417.367 | g | Used longitudinal acceleration value in the ABS. |
| AY1_ABS_int | 0x541 | 16 | 16 | Intel | Unsigned | 0 | 0.00012742 | -41.768 | -41.768 | 41.765 | g | Used lateral acceleration value in the ABS. |
| IF_variant | 0x541 | 48 | 6 | Intel | Unsigned | 0 | 1 | 0 | 0 | 63 | | external info to e.g. MS6 which dbc has to be used. This index increments on changes that make the MS6 interface incompatible to the predecessor CAN interface implementation |
| IF_revision | 0x541 | 54 | 6 | Intel | Unsigned | 0 | 1 | 0 | 0 | 63 | | external info to e.g. MS6 which dbc has to be used. This index increments with added features (rest of MS6 interface stays intact.) |
| IF_chksum | 0x541 | 60 | 4 | Intel | Unsigned | 0 | 1 | 0 | 0 | 15 | | external info to e.g. MS6 which dbc has to be used. Checksum |
| Mplx_SW_Info | 0x542 | | | | | | | | | | | Multiplexed SW Information, please refer to the dbc file. |
| SwitchPosition | 0x5C0 | 0 | 8 | Intel | Unsigned | 0 | 1 | 0 | 1 | 12 | | Used switch position of the ABS. |
| P_FA | 0x5C0 | 8 | 16 | Intel | Signed | 0 | 0.01526 | 0 | -42.5 | 425 | bar | Brake pressure on the front axle. |
| BLS | 0x5C0 | 24 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit for the brake light switch. |
| Bremse_53_cnt | 0x5C0 | 26 | 2 | Intel | Unsigned | 0 | 1 | 0 | 0 | 3 | | |
| ABS_Malfunction | 0x5C0 | 28 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit will jump to 1, if the ABS control is deactivated by a fault. |
| ABS_Active | 0x5C0 | 29 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit will jump to 1, when the ABS control is active. |
| EBD_Lamp | 0x5C0 | 30 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit will jump to 1, when the EBD is deactivated due to a fault. |

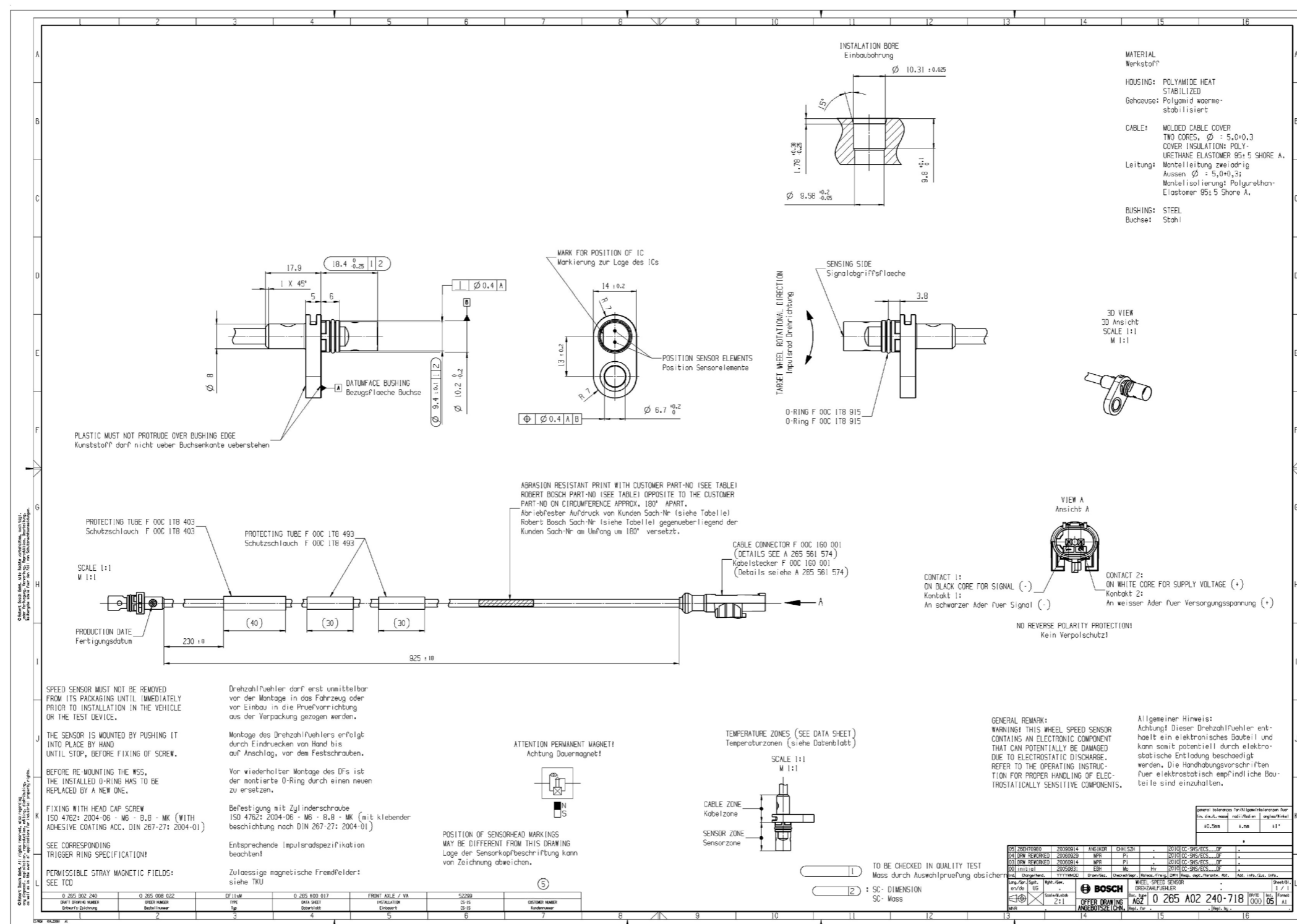
| ABS | | | | | | | | | | | | |
|------------------------------|-------|-------------|--------------|------------|------------|---------------|-------------|---------|---------|---------|------|---|
| ABS_Lamp | 0x5C0 | 31 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit will jump to 1, when the ABS control is deactivated due to a fault, switch to the off position or while working with RaceABS. |
| Diag_FL | 0x5C0 | 32 | 2 | Intel | Unsigned | 0 | 1 | 0 | 0 | 3 | | Value to show faults related to the wheel speed sensor. |
| Diag_FR | 0x5C0 | 34 | 2 | Intel | Unsigned | 0 | 1 | 0 | 0 | 3 | | 0 - Signal ok, |
| Diag_RL | 0x5C0 | 36 | 2 | Intel | Unsigned | 0 | 1 | 0 | 0 | 3 | | 1 - Wiring related fault, |
| Diag_RR | 0x5C0 | 38 | 2 | Intel | Unsigned | 0 | 1 | 0 | 0 | 3 | | 2 - Signal related fault |
| Diag_ABSUnit | 0x5C0 | 40 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit to show, if a ABS error related to the hydraulic unit is present |
| Diag_FuseValve | 0x5C0 | 41 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit to show, if a ABS error related to the fuse or power supply of the ABS valves is present. |
| Diag_FusePump | 0x5C0 | 42 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit to show, if a ABS error related to the fuse or power supply of the ABS pump is present. |
| Diag_P_FA | 0x5C0 | 43 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit to show, if the pressure sensor FA is working properly. An error is present, if the bit is 1. |
| Diag_P_RA | 0x5C0 | 44 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit to show, if the pressure sensor RA is working properly. An error is present, if the bit is 1. |
| Diag_YRS | 0x5C0 | 45 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit to show, if the yaw rate sensor is working properly. An error is present, if the bit is 1. |
| ABS_fault_info | 0x5C0 | 46 | 2 | Intel | Unsigned | 0 | 1 | 0 | 0 | 3 | | Bit matrix to show if a fault or a active fault is stored in the ABS. Bit will also show minor errors which do not shut down the ABS controller. |
| P_RA | 0x5C0 | 48 | 16 | Intel | Signed | 0 | 0.01526 | 0 | -42.5 | 425 | bar | Brake pressure on the rear axle. |
| MM5.10 | | | | | | | | | | | | |
| Name | ID | Start [Bit] | Length [Bit] | Byte Order | Value Type | Initial Value | Factor | Offset | Minimum | Maximum | Unit | Comment |
| Yaw_Rate | 0x70 | 0 | 16 | Intel | Unsigned | 0 | 0.005 | -163.84 | -163.84 | 163.83 | °/s | Measured yaw rate around the Z axle. |
| AY1 | 0x70 | 32 | 16 | Intel | Unsigned | 0 | 0.000127465 | -4.1768 | -4.1768 | 4.1765 | g | Measured lateral acceleration. |
| Roll_Rate | 0x80 | 0 | 16 | Intel | Unsigned | 0 | 0.005 | -163.84 | -163.84 | 163.835 | °/s | Measured roll rate around the X axle. |
| AX1 | 0x80 | 32 | 16 | Intel | Unsigned | 0 | 0.000127465 | -4.1768 | -4.1768 | 4.1765 | g | Measured longitudinal acceleration. |
| AZ | 0x576 | 32 | 16 | Intel | Unsigned | 0 | 0.000127465 | -4.1768 | -4.1768 | 4.1765 | g | Measured vertical acceleration. |
| Other IDs in use from ABS M5 | | | | | | | | | | | | |
| | 0x140 | | | | | | | | | | | |
| | 0x141 | | | | | | | | | | | |
| | 0x142 | | | | | | | | | | | |
| | 0x143 | | | | | | | | | | | |
| | 0x340 | | | | | | | | | | | |
| | 0x341 | | | | | | | | | | | |
| | 0x343 | | | | | | | | | | | |
| | 0x75 | | | | | | | | | | | |

14 CAN Protocol V15 customer from 0400 onwards

| | | | | | | | | | | | | |
|------------------------------|------------|-------------|--------------|------------|------------|---------------|----------|--------|---------|---------|------|--|
| ABS-M5 CAN | Version 15 | 16.02.2018 | | | | | | | | | | |
| Customer version | | | | | | | | | | | | |
| Input | | | | | | | | | | | | |
| Name | ID | Start [Bit] | Length [Bit] | Byte Order | Value Type | Initial Value | Factor | Offset | Minimum | Maximum | Unit | Comment |
| ABS_Switchposition | 0x24C | 0 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 11 | | Channel to send the swich position via CAN to the ABS. |
| Rate must be 10 ms / 100 Hz. | | | | | | | | | | | | |
| ABS | | | | | | | | | | | | |
| Name | ID | Start [Bit] | Length [Bit] | Byte Order | Value Type | Initial Value | Factor | Offset | Minimum | Maximum | Unit | Comment |
| RG_VL_Bremse2 | 0x24A | 0 | 16 | Intel | Unsigned | 0 | 0.015625 | 0 | 0 | 100 | m/s | Wheel speed direct FL |
| RG_VR_Bremse2 | 0x24A | 16 | 16 | Intel | Unsigned | 0 | 0.015625 | 0 | 0 | 100 | m/s | Wheel speed direct FR |
| RG_HL_Bremse2 | 0x24A | 32 | 16 | Intel | Unsigned | 0 | 0.015625 | 0 | 0 | 100 | m/s | Wheel speed direct RL |
| RG_HR_Bremse2 | 0x24A | 48 | 16 | Intel | Unsigned | 0 | 0.015625 | 0 | 0 | 100 | m/s | Wheel speed direct RR |
| SPK_FA | 0x342 | 0 | 8 | Intel | Unsigned | 0 | 0.05 | 0 | 0 | 10 | cm3 | Fill level of the fluid reservoir of the front axle. |
| SPK_RA | 0x342 | 8 | 8 | Intel | Unsigned | 0 | 0.05 | 0 | 0 | 10 | cm3 | Fill level of the fluid reservoir of the rear axle. |
| WheelQuality_FL | 0x342 | 32 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 32 | | Identification bit for wheel sped signal disturbances, check the sensor and the surrounding if bit is > 1. |
| WheelQuality_FR | 0x342 | 40 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 32 | | |
| WheelQuality_RL | 0x342 | 48 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 32 | | |
| WheelQuality_RR | 0x342 | 56 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 32 | | |
| Brake_bal_at50 | 0x560 | 16 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 60 | Bar | Calculated rear axle brake pressure if the front pressure is at 50 bar. |
| Brake_bal_at50_advice | 0x560 | 24 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 60 | Bar | Recommended rear axle brake pressure if the front pressure is at 50 bar. |
| Brake_bal_proc | 0x560 | 32 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 100 | % | Percental brake balance on the front axle. |
| Brake_bal_proc_advice | 0x560 | 40 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 100 | % | Recommended percental brake balance on the front axle. |
| Diag_FL | 0x541 | 0 | 2 | Intel | Unsigned | 0 | 1 | 0 | 0 | 3 | | Value to show faults related to the wheel speed sensor. |
| Diag_FR | 0x541 | 2 | 2 | Intel | Unsigned | 0 | 1 | 0 | 0 | 3 | | 0 - Signal ok, |
| Diag_RL | 0x541 | 4 | 2 | Intel | Unsigned | 0 | 1 | 0 | 0 | 3 | | 1 - Wiring related fault, |
| Diag_RR | 0x541 | 6 | 2 | Intel | Unsigned | 0 | 1 | 0 | 0 | 3 | | 2 - Signal related fault |
| Diag_ABSUnit | 0x541 | 8 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 0 | | Bit to show, if an ABS error related to the hydraulic unit is present |
| Diag_FusePump | 0x541 | 9 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 0 | | Bit to show, if an ABS error related to the fuse or power supply of the ABS pump is present. |
| Diag_FuseValve | 0x541 | 10 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 0 | | Bit to show, if an ABS error related to the fuse or power supply of the ABS valves is present. |
| SwitchPosition | 0x5C0 | 0 | 8 | Intel | Unsigned | 0 | 1 | 0 | 1 | 12 | | Used switch position of the ABS. |
| P_FA | 0x5C0 | 8 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 255 | bar | Brake pressure on the front axle. |
| P_RA | 0x5C0 | 16 | 8 | Intel | Unsigned | 0 | 1 | 0 | 0 | 255 | bar | Brake pressure on the rear axle. |
| BLS | 0x5C0 | 24 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit for the brake light switch. |
| ABS_Malfunction | 0x5C0 | 28 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 0 | | Bit will jump to 1, if the ABS control is deactivated by a fault. |
| ABS_Active | 0x5C0 | 29 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit will jump to 1, when the ABS control is active. |

| ABS | | | | | | | | | | | | |
|------------------------------|-------|-------------|--------------|------------|------------|---------------|-------------|---------|---------|---------|------|---|
| EBD_Lamp | 0x5C0 | 30 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit will jump to 1, when the EBD is deactivated due to a fault. |
| ABS_Lamp | 0x5C0 | 31 | 1 | Intel | Unsigned | 0 | 1 | 0 | 0 | 1 | | Bit will jump to 1, when the ABS control is deactivated due to a fault, switched to the off position or while working with RaceABS. |
| AX1_Bremse60 | 0x5C0 | 32 | 16 | Intel | Unsigned | 0 | 0.00012742 | -4.1768 | -4.1768 | 4.17367 | g | Used longitudinal acceleration value in the ABS. |
| AY1_Bremse60 | 0x5C0 | 48 | 16 | Intel | Unsigned | 0 | 0.00012742 | -4.1768 | -4.1768 | 4.1765 | g | Used lateral acceleration value in the ABS. |
| MM5.10 | | | | | | | | | | | | |
| Name | ID | Start [Bit] | Length [Bit] | Byte Order | Value Type | Initial Value | Factor | Offset | Minimum | Maximum | Unit | Comment |
| Yaw_Rate | 0x70 | 0 | 16 | Intel | Unsigned | 0 | 0.005 | -163.84 | -163.84 | 163.83 | °/s | Measured yaw rate around the Z axle. |
| AY1 | 0x70 | 32 | 16 | Intel | Unsigned | 0 | 0.000127465 | -4.1768 | -4.1768 | 4.1765 | g | Measured lateral acceleration. |
| Roll_Rate | 0x80 | 0 | 16 | Intel | Unsigned | 0 | 0.005 | -163.84 | -163.84 | 163.835 | °/s | Measured roll rate around the X axle. |
| AX1 | 0x80 | 32 | 16 | Intel | Unsigned | 0 | 0.000127465 | -4.1768 | -4.1768 | 4.1765 | g | Measured longitudinal acceleration. |
| AZ | 0x576 | 32 | 16 | Intel | Unsigned | 0 | 0.000127465 | -4.1768 | -4.1768 | 4.1765 | g | Measured vertical acceleration. |
| Other IDs in use from ABS M5 | | | | | | | | | | | | |
| | 0x140 | | | | | | | | | | | |
| | 0x141 | | | | | | | | | | | |
| | 0x142 | | | | | | | | | | | |
| | 0x143 | | | | | | | | | | | |
| | 0x340 | | | | | | | | | | | |
| | 0x341 | | | | | | | | | | | |
| | 0x343 | | | | | | | | | | | |
| | 0x75 | | | | | | | | | | | |

15.2 Offer Drawing Wheel Speed Sensor



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Kabelbaumstecker: RB-Kompaktstecker 1.1a nach RB-Zeichnung
A 928 000 453, 3-polig, Kodierung I, BDK-Kontakte vergoldet,
0,5-1,0mm²

WIRE HARNESS CONNECTOR : RB KOMPAKT CONECOR 1.1A
ACC. TO RB DRAWING A 928 000 453, 3 PINS, CODING I.
BDK TRMINALS GOLD-PLATED, 0,5-1,0 mm²

Werkstoff: 1.4542 (DIN Norm)
MATERIAL: 1.4542 (DIN Norm)

Am Sensor: RB-Kompaktstecker 1.1 nach RB-Zeichnung
1 928 A00 755 Variante B vom 11.05.2004 (in hochschuettelfester Ausfuehrung)
3-polig, Kodierung I, Kontakte vergoldet
Werktoff: PBT GF30

AT SENSOR: RB KOMPAKT CONNECTOR 1.1 ACC. TO RB DRAWING
1 928 A00 755 VARIANT B FROM 11.05.2004 (IN HIGH VIBRATION RESISTANT DESIGN)
3 PINS, CODING I, TERMINALS GOLD-PLATED
MATERIAL: PBT GF30

Pin 3: Versorgung (+)
Pin 3: SUPPLY VOLTAGE (+)

Pin 2: Ausgang
Pin 2: OUTPUT

Pin 1: Masse (-)
Pin 1: GROUND (-)

Herkunftsbezeichnung
MARKING OF ORIGIN
Auf der Rueckseite:
ON THE BACK:

>PBT-
GF30<

Werknummer
NUMBER OF PLANT

Typ-Aufschrift
TYPE DESIGNATION

Stanzeinzug max. 0,6
STAMP PULL-IN MAX. 0,6

Fertigungsdatum
und Seriennummer
unverschlüsselt
DATE OF PRODUCTION
AND SERIAL NUMBER
NOT ENCODED

Wichtige Hinweise:

- RB-Gewahrleistung fuer die Funktion des Stecksystems nur bei Verwendung der in dieser Angebotszeichnung vorgeschriebenen Gegenstecker-Systemteile.
- Erste Abstuetzstelle des Kabels max. 150mm nach der Steckverbindung (gestreckte Kabellaenge). Sie muss auf dem Sensortraeger liegen.
- Abwicklung des Kabels (Abweichung von der geraden Linie) zwischen Kabelabgang am Sensor und erster Abstuetzstelle: 20...90°
- Zulaessiger Biegeradius des Kabels bis zur ersten Abstuetzstelle: R ≥ 50mm
- Einbauvorschrift siehe zugehoerige Railangebotszeichnung bzw. Rail-TKU
- Max. zulassige Einschraubbelastung: 35Nm
- Montagehinweis siehe Y 261 F26 048

Zu beachten: Sensor ist durch aufgesteckten Gegenstecker vor Eindringen von Wasser zu schuetzen.

IMPORTANT NOTES

- RB WARRANTY WILL COVER THE FUNCTION OF THE CONNECTOR SYSTEM ONLY IN CASE OF COMBINATION WITH HARNESS CONNECTOR SYSTEM PARTS ACCORDING TO THIS OFFER DRAWING.
- FIRST CABLE MOUNTING POINT MAX. 150 MM AFTER THE PLUG (STRAIGHT CABLE LENGTH). IT MUST BE LOCATED ON THE SENSOR CARRIER.
- ANGLE OF BENING THE CABLE (DEVIATION FROM STRAIGHT LINE) BETWEEN CABLE EXIT AT SENSOR AND FIRST MOUNTING POINT: 20...90°.
- ADMISSIBLE BENDING RADIUS OF THE CABLE UP TO THE FIRST CABLE MOUNTING POINT: R ≥ 50MM.
- INSTALLATION INSTRUCTIONS SEE CORRESPONDING OFFER DRAWING RAIL RESPECTIVELY TKU RAIL
- MAX. AUTHORIZED STRESS TO SCREW IN: 35Nm
- ASSEMBLY INSTRUCTIONS SEE Y 61 F26 048

ATTENTION: USE HARNESS CONNECTOR FOR PROTECTION AGAINST WATER INGRESS.

Stutzen nach unten gerichtet.

Empfohlene Lage: 0...90°
in allen Richtungen zur Senkrechten.

ORIFICE DIRECTED DOWNWARDS.

RECOMMENDED POSITION: 0...90°
FROM VERTICAL.

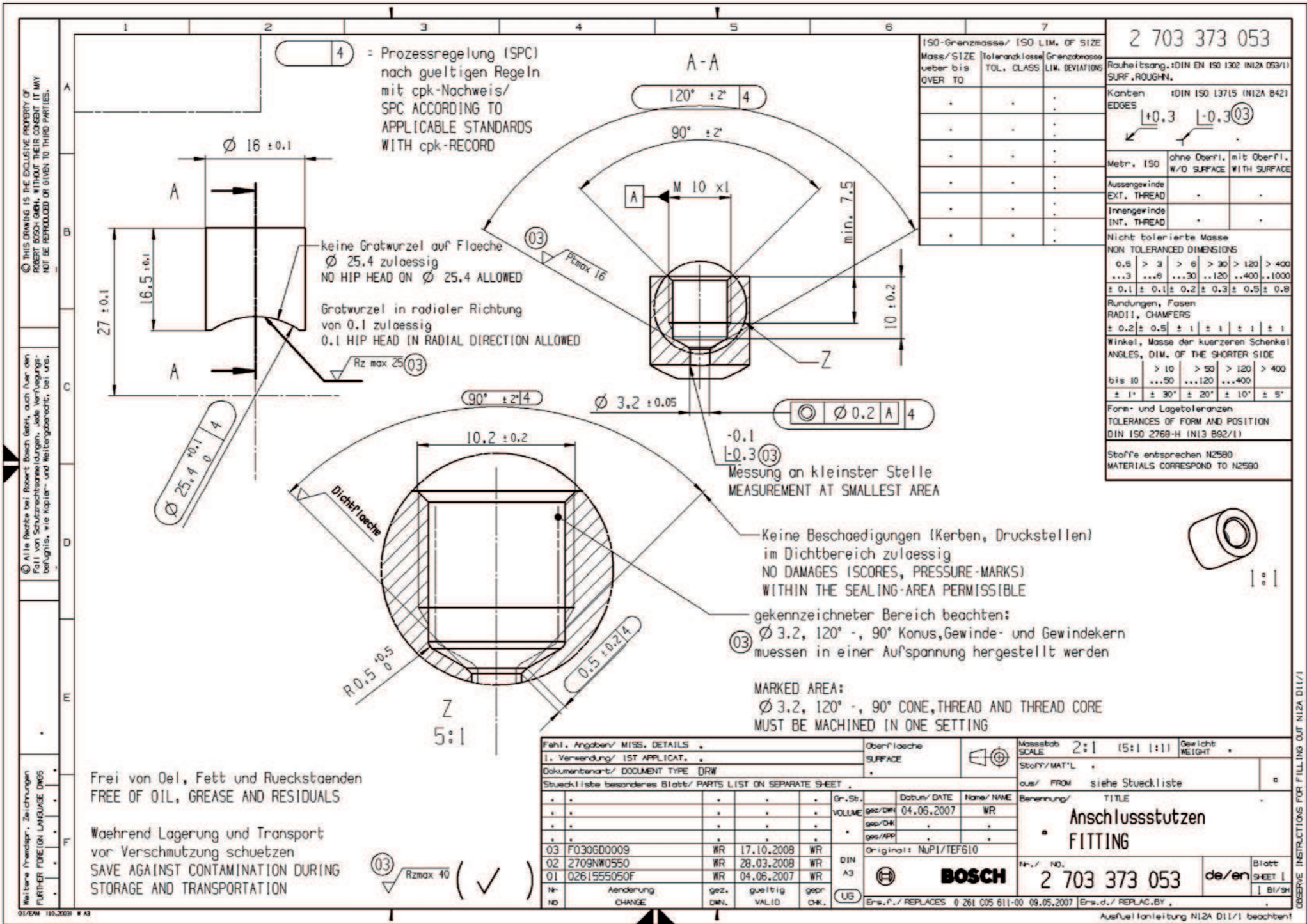
| General tolerances for all dimensions unless otherwise specified | | |
|--|--------------|---------------|
| lin. dim./L-masse | radii/Radien | angles/Winkel |
| ±1mm | ±1mm | ±5° |

| | | | | | | |
|-------------------|--------------------|-------------------------------|---|---------------------------------------|--------------------------------|-----------------------|
| 02 2BEH93318 | 20111122 | Hi | Sw | Sv | 2130 GS-SI/ENS | . |
| 01 0261545040 | 20071220 | De | Kr | . | 2130 GS-SI/ENS | . |
| 00 initial | 20051214 | De | . | . | null Migration-ORG: | Orig: GS-SI/ENS |
| Incl. Change/Änd. | YYYYMMDD | Drawn/Bez. | Checked/Spr. | Released/Freig. | BWN Resp. depts./Verantw. Abt. | Add. info./Zus. Info. |
| Lang./Spr.: en/de | Syst. US | Richt./Riv.: 35,3 g | BOSCH HIGH PRESSURE SENSOR HOCHDRUCKSENSOR | | | |
| MNR | Scale/Maststab 2:1 | OFFER DRAWING ANGEBOTSZEICHN. | | | | |
| Doc. type AGZ | | 0 261 A04 407 | | DS-HD-KV4.2 280bar DS-HD-KV4.2 280bar | | |
| Repl. for . | | Repl. by . | | Sheet/Bl. 1 / 1 Form A2 | | |

CJ NEW 104.20081 A2

15.4 Mounting Instructions Brake Pressure Sensor

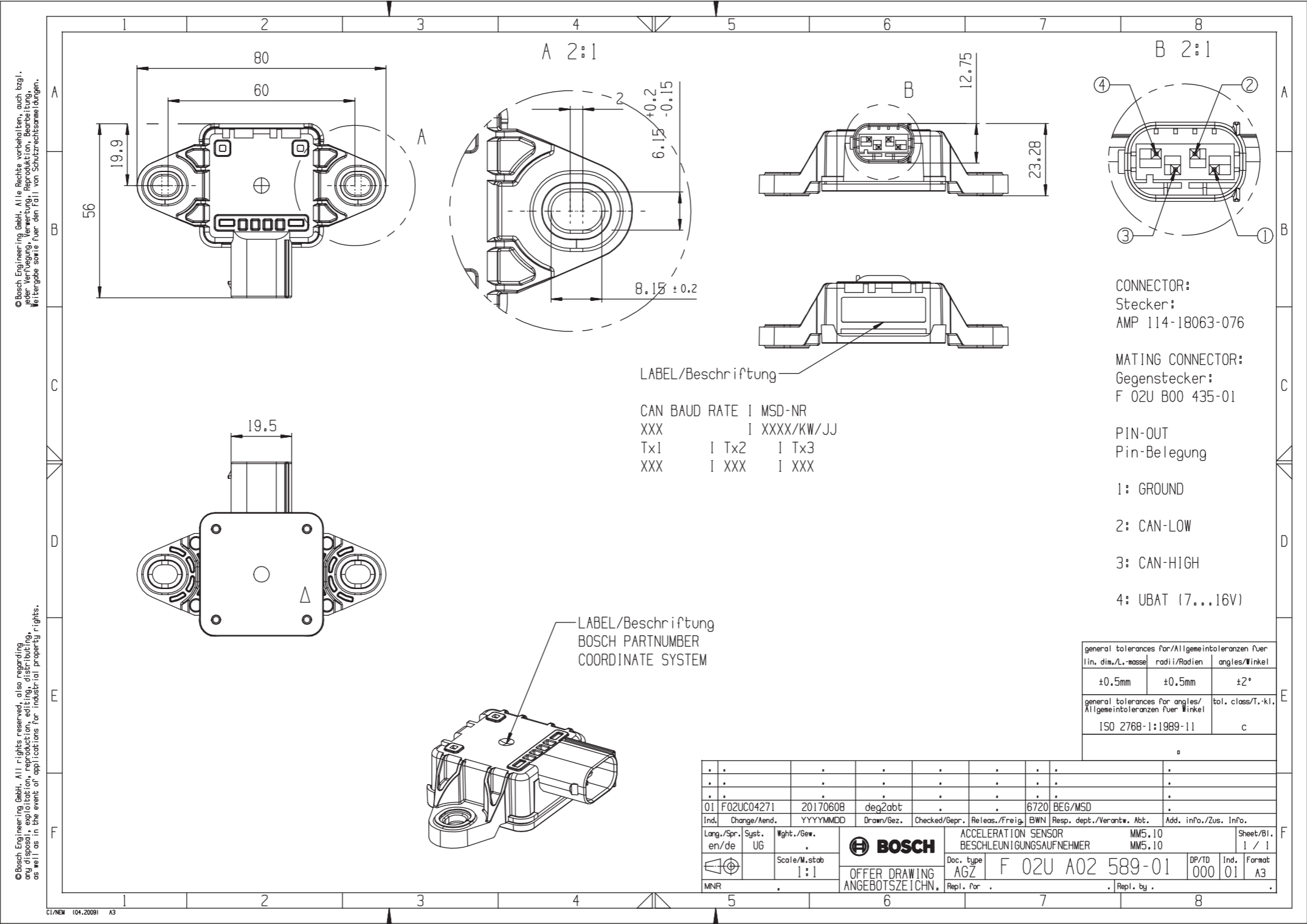
Bosch Gasoline Systems, P81 | 2703373053 DRW 001 03 | SAP-Status 40 | Labor F28 | Change F030GD000901



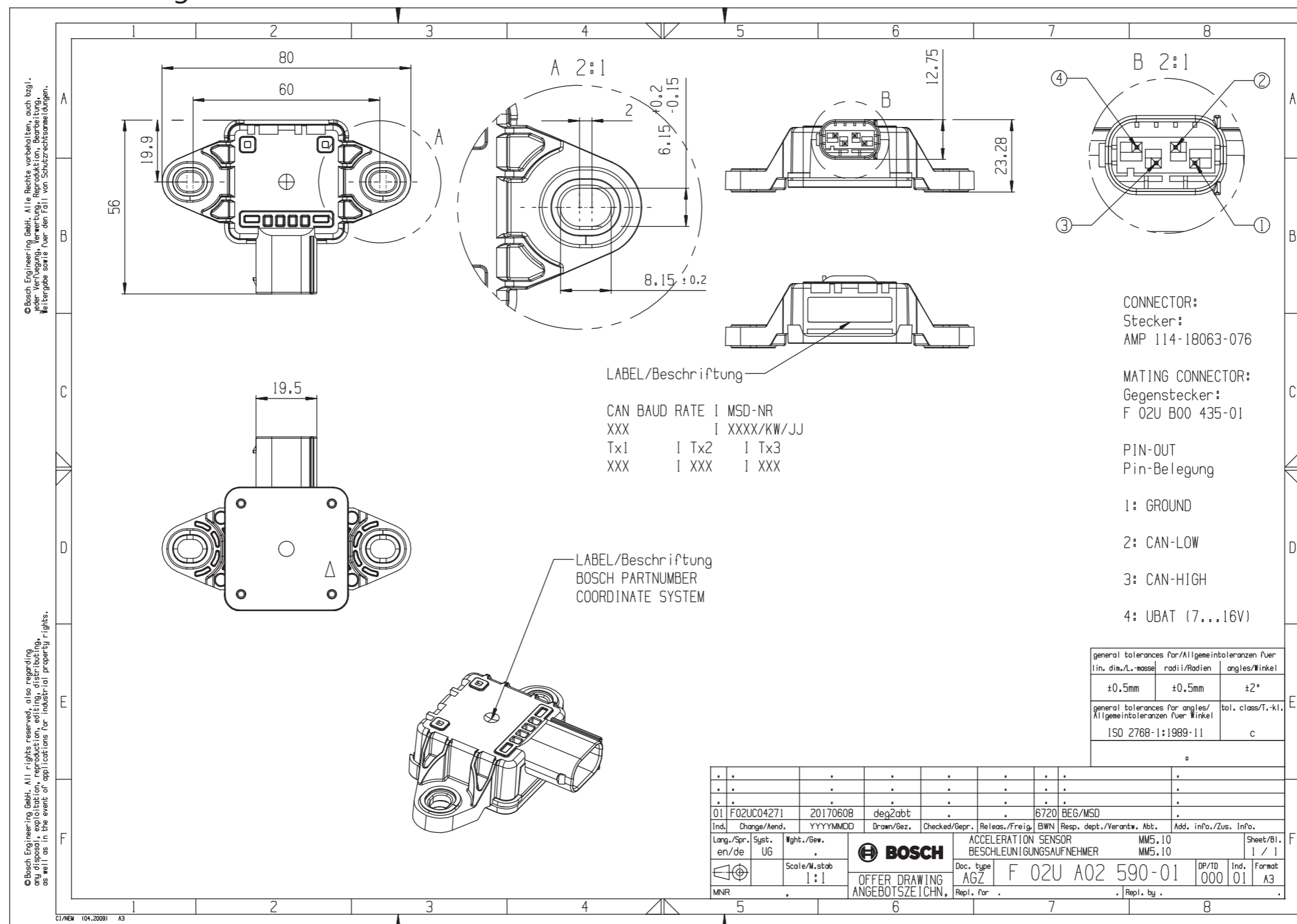
Ausdrucke und Kopien unterliegen nicht dem Änderungsdienst

Ausgedruckt am 13.02.2009 von ole2fe

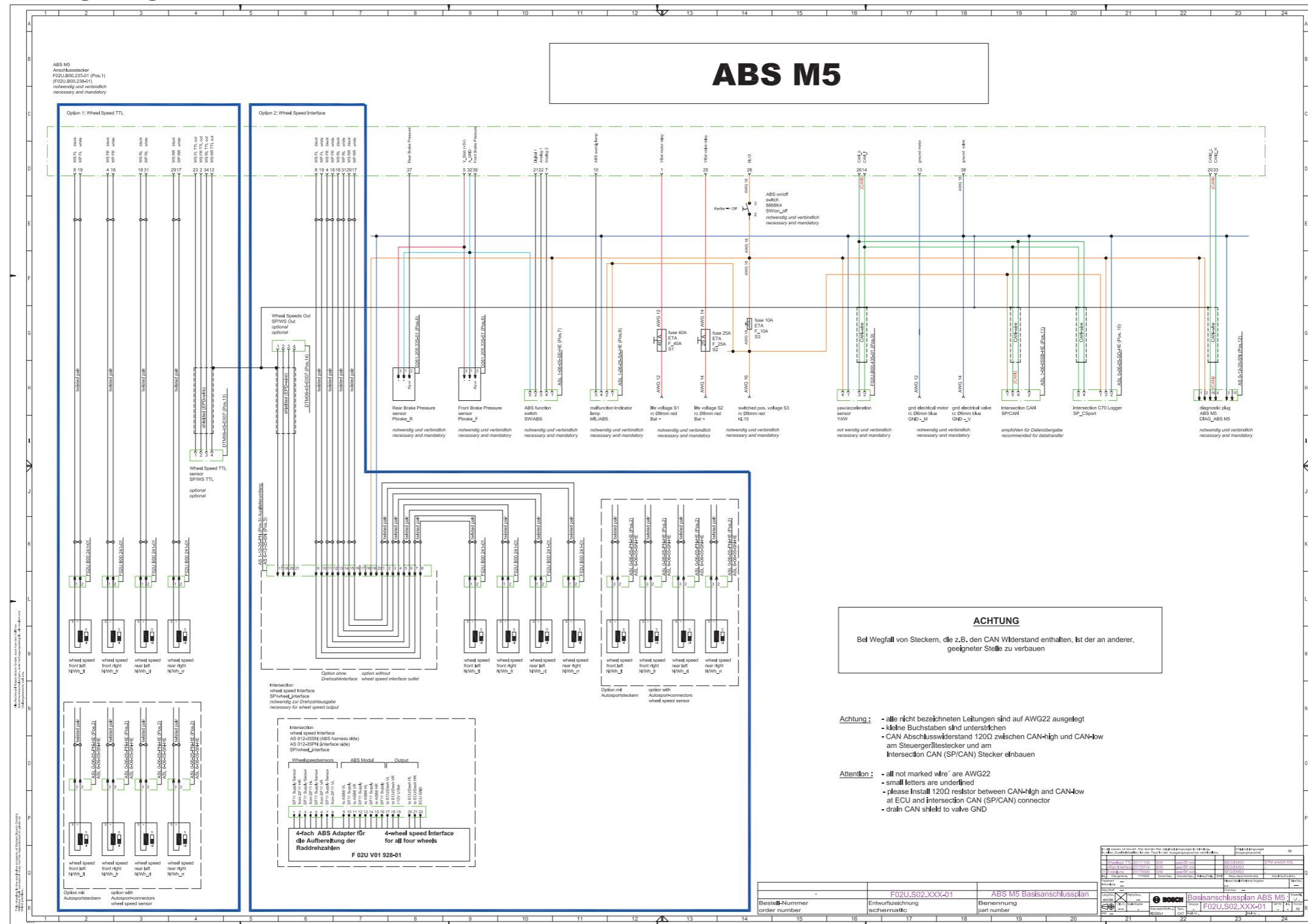
15.5 Offer Drawing Yaw/Acceleration Sensor 500 kbaud



15.6 Offer Drawing Yaw/Acceleration Sensor 1 Mbaud



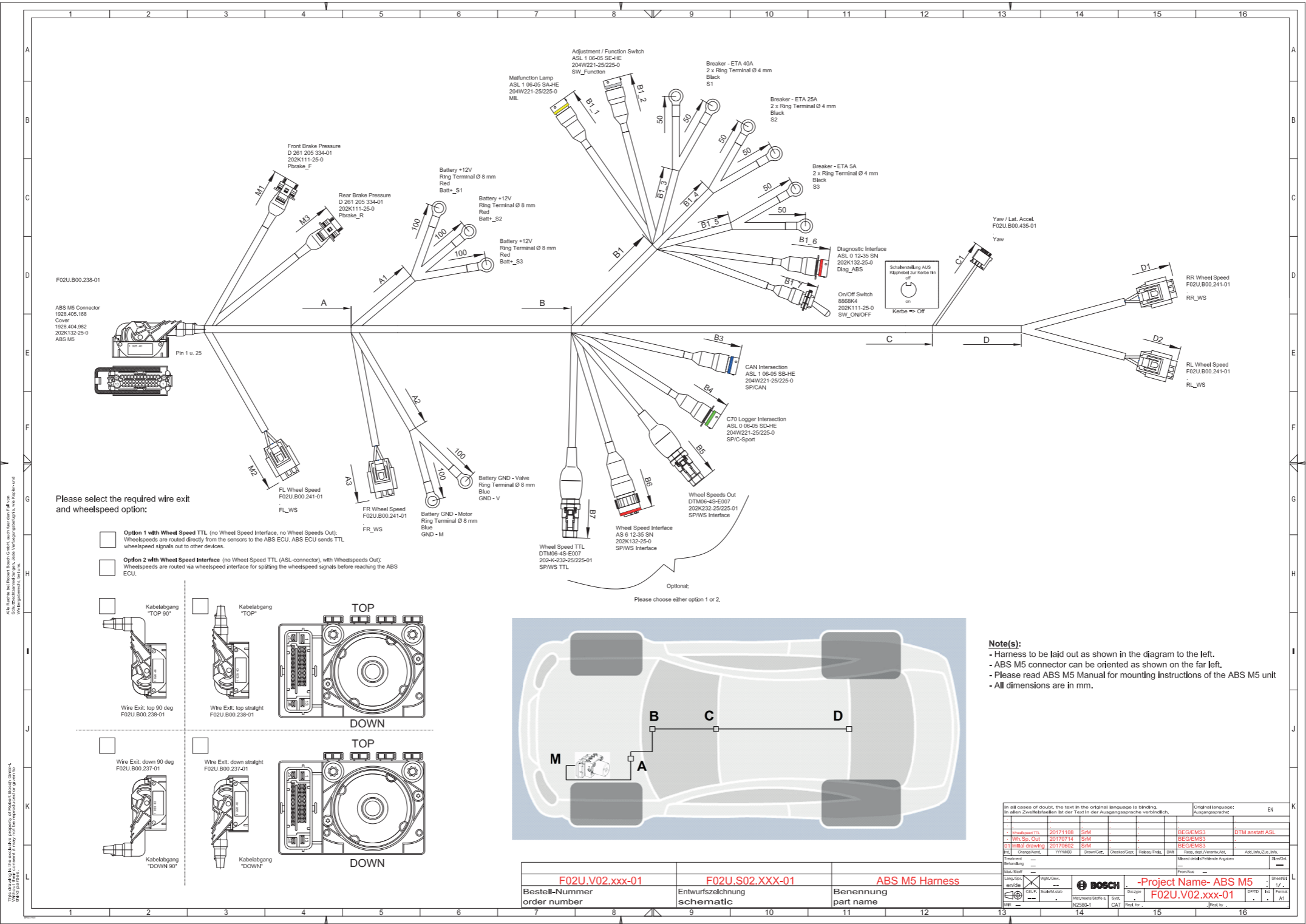
15.7 Wiring Diagram



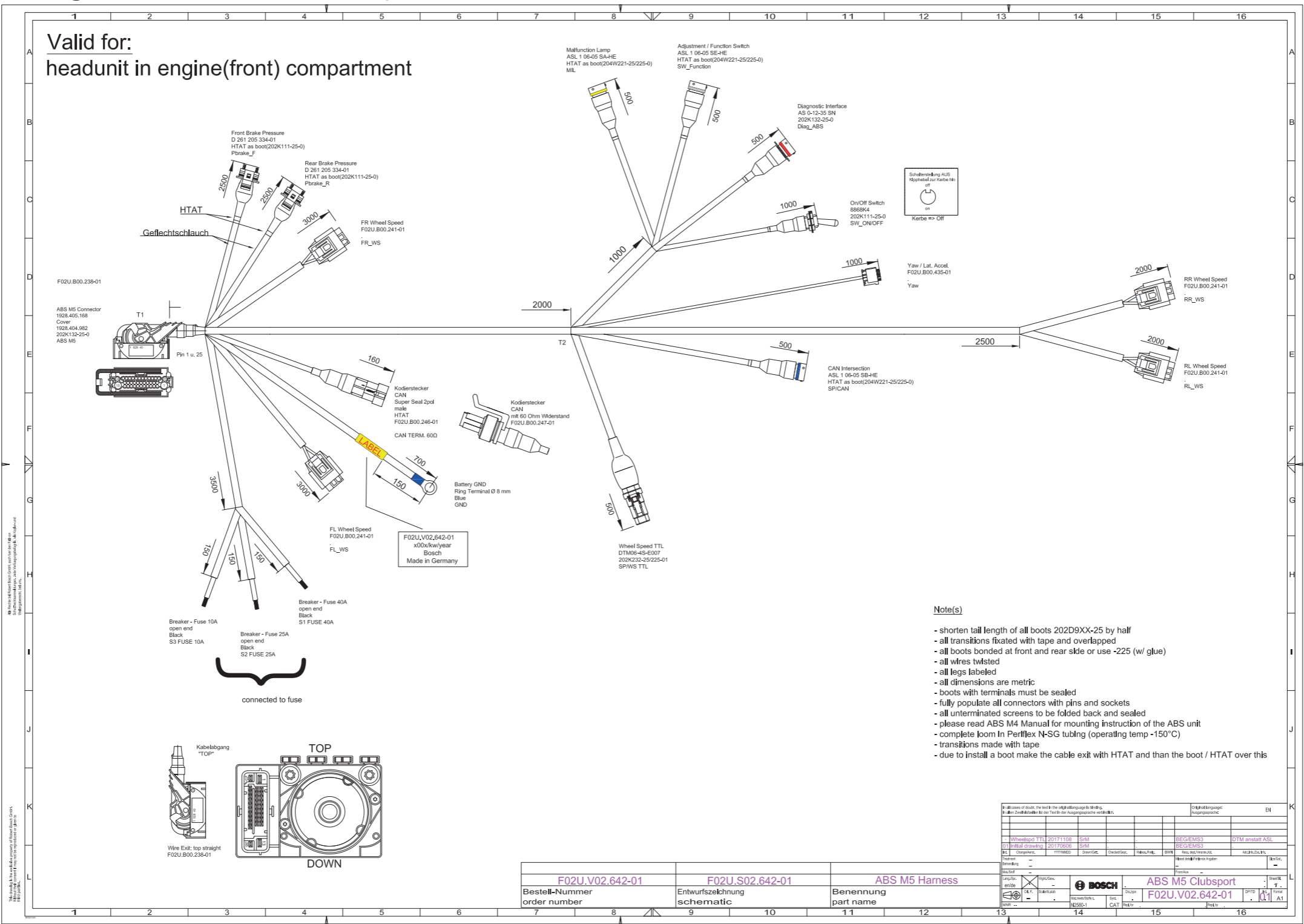
ABS_M5_Kit_Manual



15.9 Wiring Harness



15.10 Wiring Harness ABS M5 Clubsport



[illegible]

Bosch Engineering GmbH

Motorsport
Robert-Bosch-Allee 1
74232 Abstatt

www.bosch-motorsport.com